

Piezoelectric Micromachined Ultrasonic Transducers in Consumer Electronics

the Next *Little* Thing?

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Seminar, Tohoku University
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2030 Vision for MEMS



Sensors

- New modalities
- Ultralow power
- Low cost
- Small size

Next 15 years:

- IoT
- Teraswarm
- Trillion Sensors

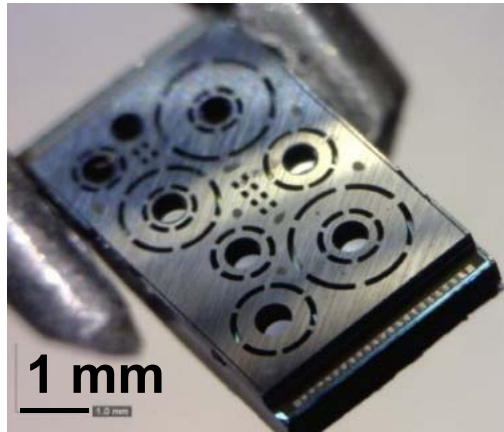
Mobile

2000-2015

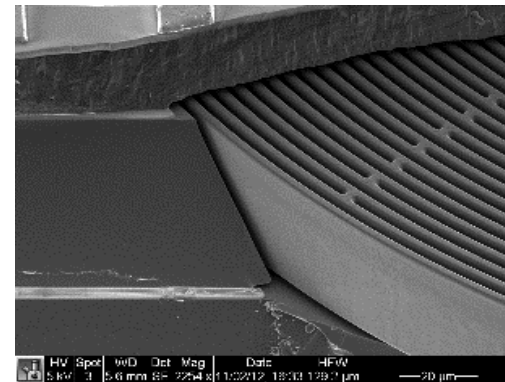
[J. Rabaey, ASPDAC'08]

Horsley Group Current Research

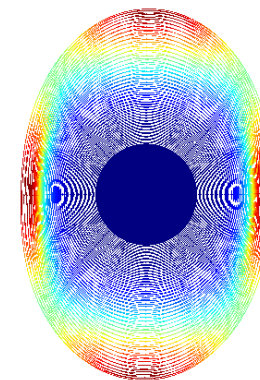
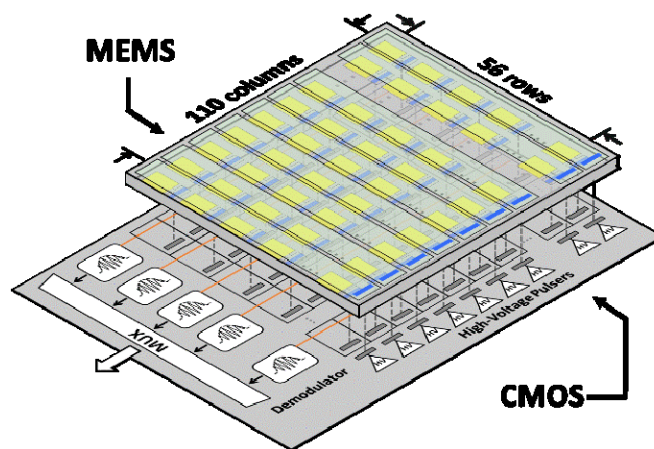
Low-Power Microsensors



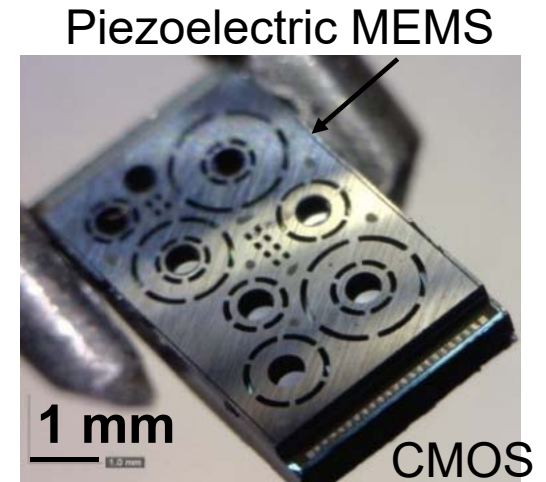
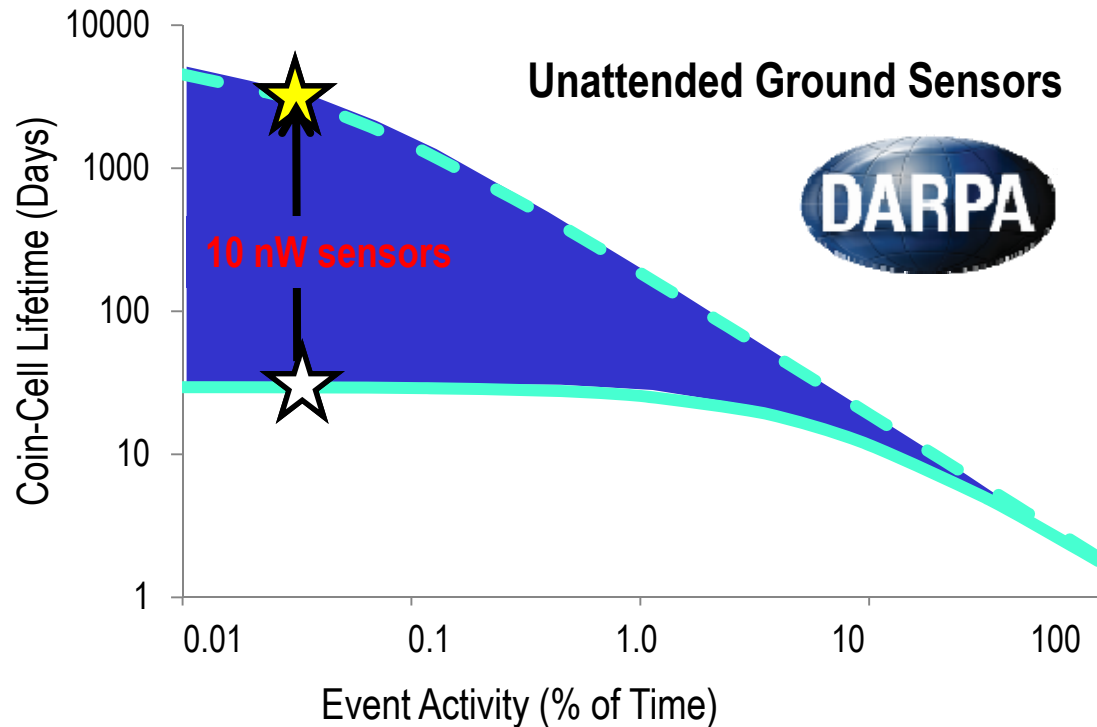
Dynamics & Control Issues in MEMS



Ultrasonics & Acoustics



Ultralow Power Sensors



- **Program Goals:**

- Accelerometer & microphone < 10 nW (10,000x below state-of-the-art)
- On-board analog/digital signal processing to recognize events

- **Our innovations**

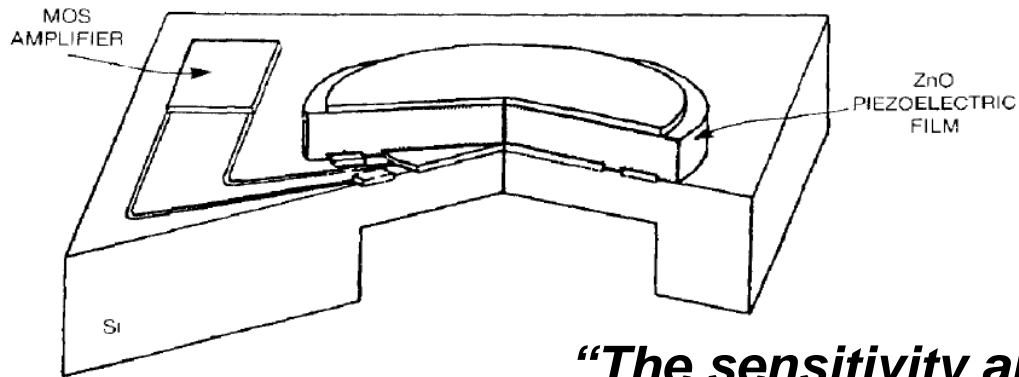
- Passive amplification at the transducer level
- Zero-bias voltage piezoelectric sensors

PMUTs in Consumer Electronics

Outline

- History and motivation
- Air-coupled ultrasonic transducers
- Time of Flight (ToF) rangefinding
- Phased-array ultrasonics
- Ultrasonic Fingerprint sensor

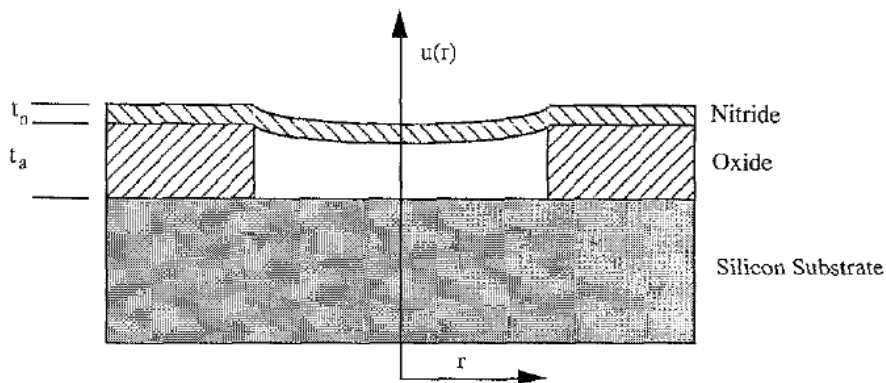
30+ Years of MUTs



PMUT

Royer et al (Honeywell)
SNA 1983

“The sensitivity and SNR of the ZnO acoustic sensor ... do not compare well with ... commonly used electret microphones”

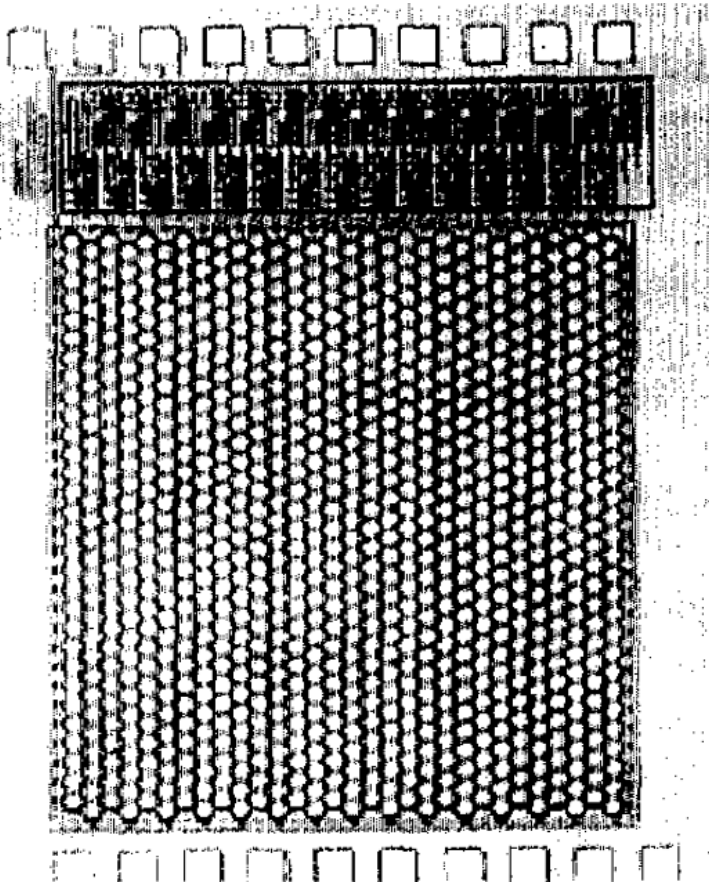


CMUT

Haller & Khuri-Yakub
(Stanford)
IUS 1994

“MUTs enjoy the inherent advantages of microfabrication, which include **low cost**, **array fabrication**, and the possibility to **integrate electronics** either on chip or as a multi-chip module.”

Integration demonstrated 20 years ago(!)



30x30 CMUT Array

Surface micromachined ultrasound transducers in CMOS technology

Eccardt, Niederer, Scheiter,
Hierold (Siemens)
IUS 1996

*“new microfabrication technologies
have emerged, allowing a highly
reproducible fabrication of
electrostatically driven membranes.”*

20 Years of Inertial Sensors

A lot has happened in two decades

1990's Gyroscope



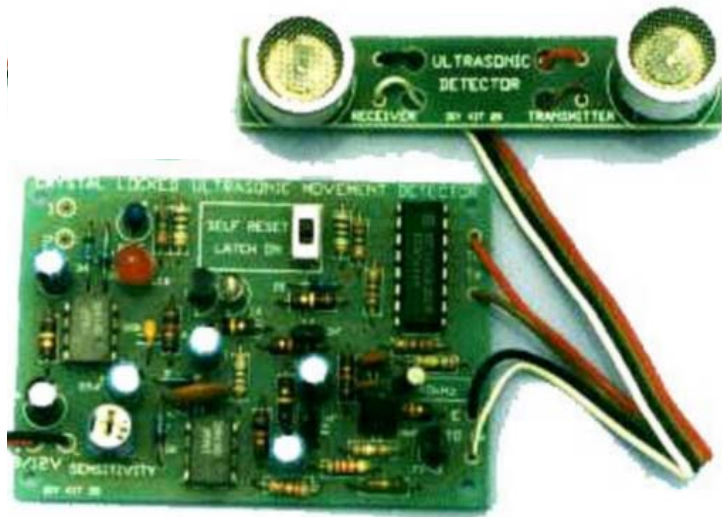
2016 Gyroscope



20 Years of Ultrasonic Sensors

A different story...

1990's Ultrasonic
Rangefinder



- Discrete, thru-hole electronics
- Big U/S transducers

2016 Ultrasonic
Rangefinder



- IC replaces many discretes
- Same old U/S transducer

What's New Today?

Technology

- Piezoelectric materials greatly improved
- Well-developed manufacturing infrastructure
 - MEMS foundries, packaging & test suppliers

Market

- Strong market pull for new sensors
 - IoT, drones, autonomous vehicles, AR/VR, new interface technology
- Every flagship phone needs a fingerprint sensor

Outline

- History and motivation
- **Air-coupled ultrasonic transducers**
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Observations from Nature



Uses ultrasound to navigate

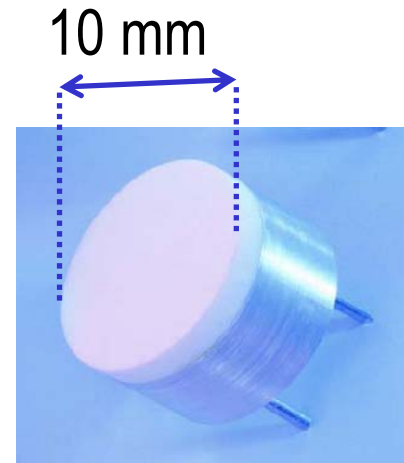
Identifies insects from wing velocity

Targets mosquitoes from 80 cm away

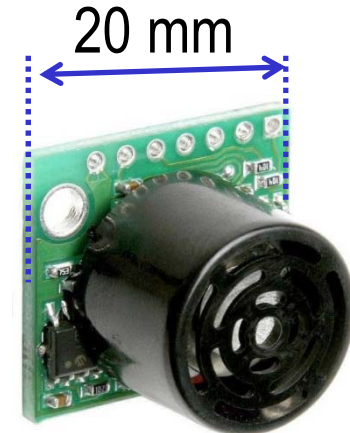
[D.R. Griffin, J. Animal Behaviour, 1960]

Existing Ultrasonic Transducers

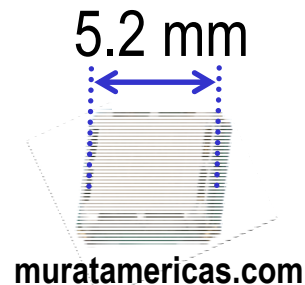
- Advantages:
 - High output pressure
 - Directional, if desired
- Disadvantages:
 - Inefficient coupling to air
 - Matching layers required
 - Too big for consumer electronics
 - Dumb sensor. Lots of external electronics required.



senscomp.com

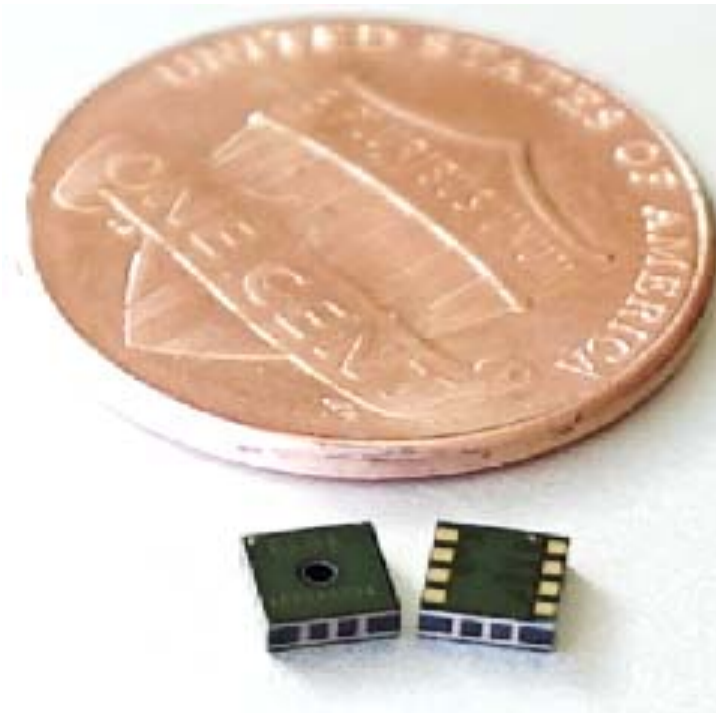


maxbotix.com



muratamericas.com

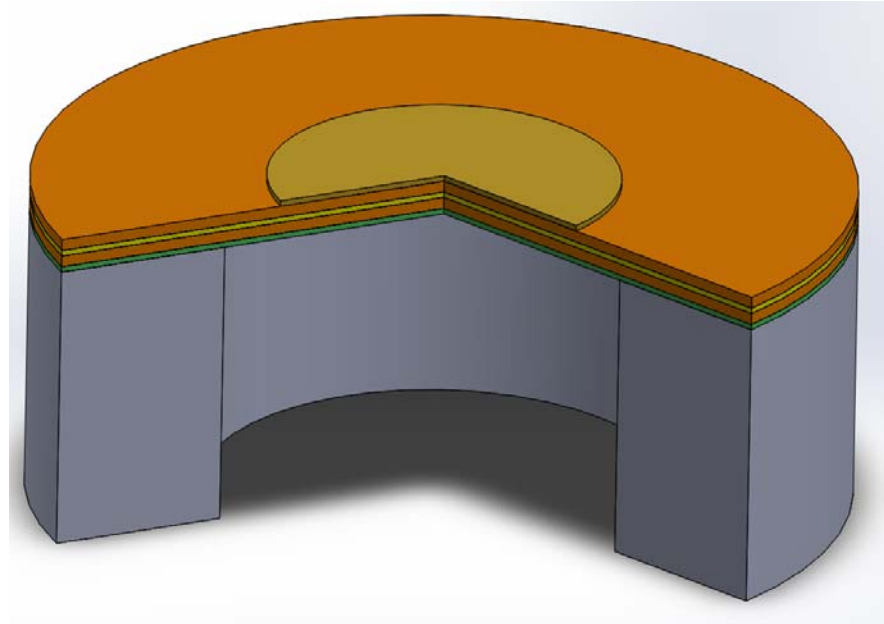
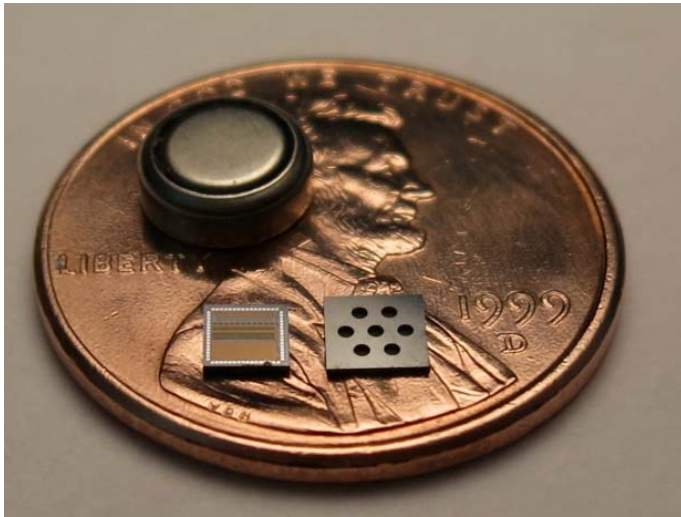
Micromachined Ultrasonic Transducers



- Extremely low power (15 μ W)
- Long range > 1 m
- Small size
 - 1000x smaller volume than conventional U/S transducer
- Digital interface
 - All signal processing performed on-chip
 - Autonomous operation for always-on sensing (host CPU can be in sleep mode)



Features of MUTs



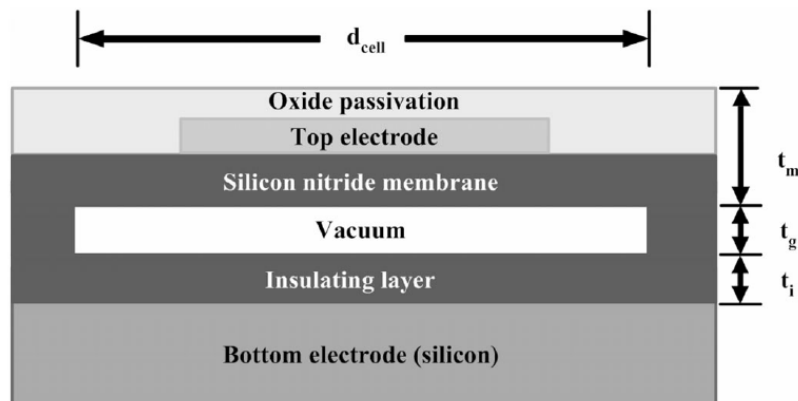
- Suspended plate structure
- Increased coupling due to low acoustic impedance
- Array fabrication possible
- Micro-patterning allows mechanics to be modified

Actuating Air-Coupled MUTs

Want:

- Large output pressure despite air's low acoustic impedance
 - Large transducer displacement
 - Piezoelectric Actuation

Capacitive (CMUT)



Wygant et al., IEEE TUFFC 2009

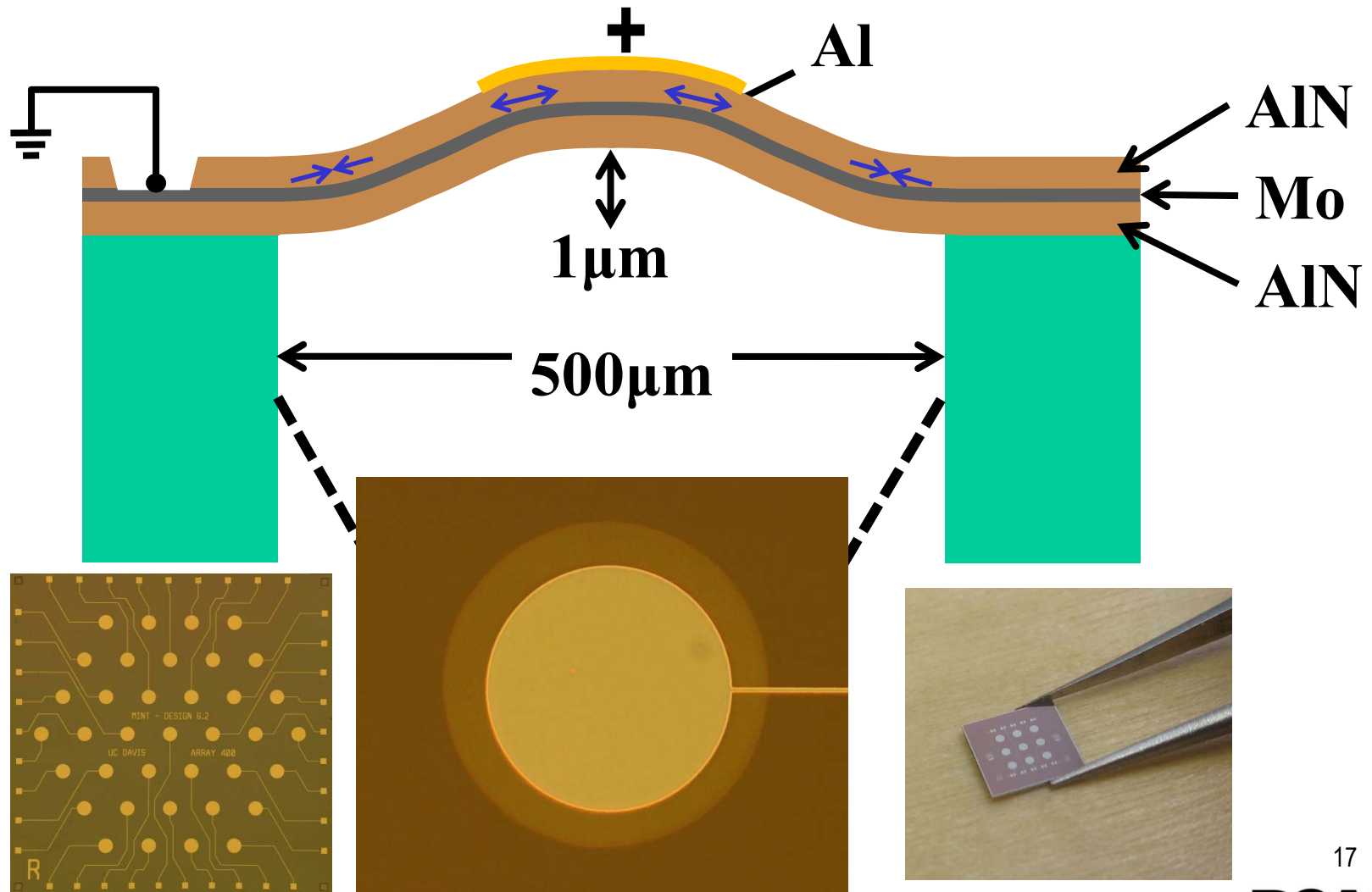
Piezoelectric (PMUT)



S. Shelton et al., IEEE IUS, 2009

R. Przybyla et al., IEEE Sensors J., 2011

Aluminum Nitride (AlN) PMUT Cross Section



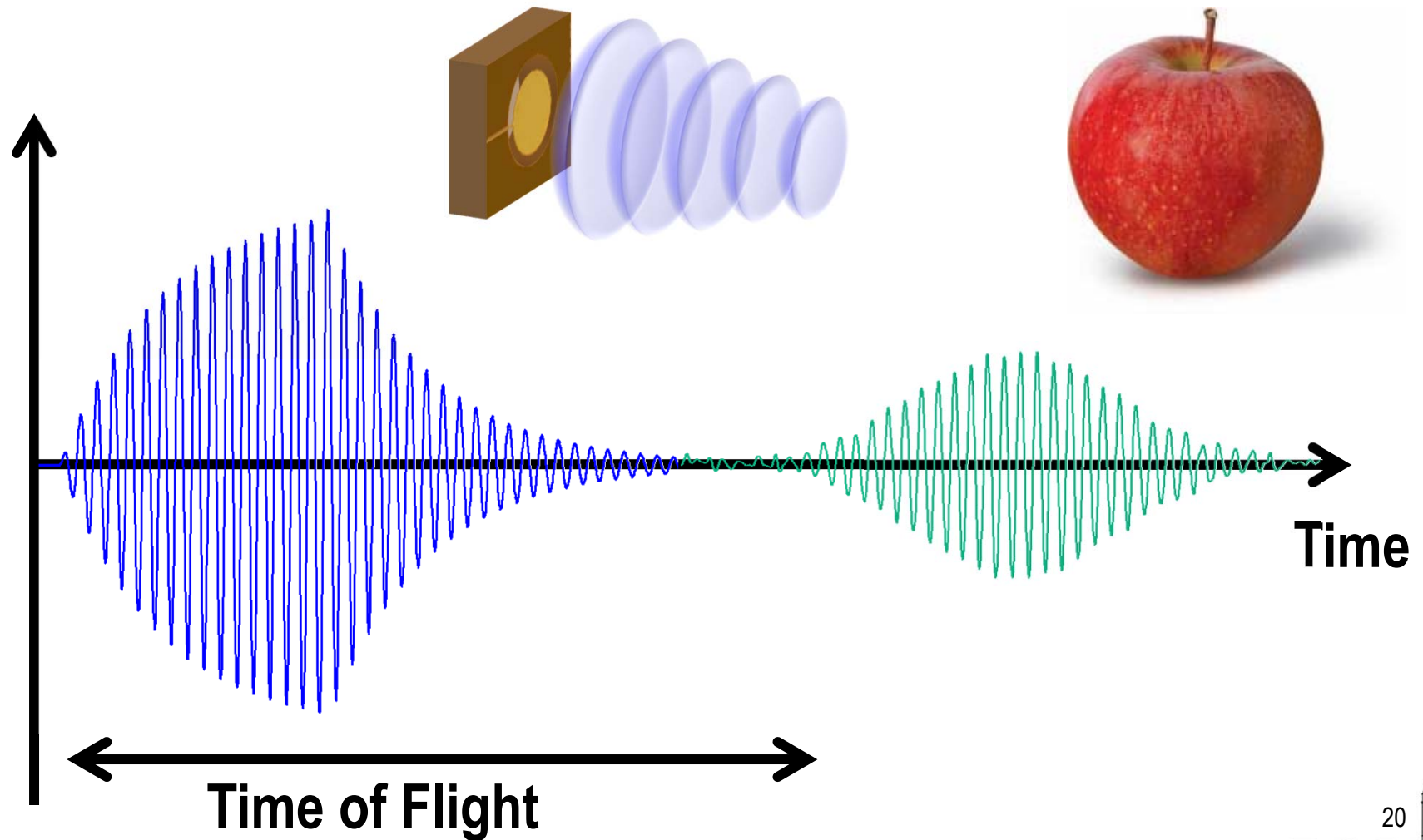
Comparing Piezoelectric Materials: Materials for PMUTs

| Metric | Property | Units | AlN | PZT | ZnO |
|-------------------------|--------------------------------------|-------------------|--------------|--------------|-------|
| Transmitter Sensitivity | $e_{31,f}$ | C m ⁻² | -1.05 | -14.9 | -1.0 |
| | ϵ_{33} | - | 10.5 | 1020 | 10.9 |
| Receiver Sensitivity | $e_{31,f} / \epsilon_{33}\epsilon_0$ | GV/m | -11.3 | -1.64 | -10.3 |

Outline

- History and motivation
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- Phased-array ultrasonics
- Ultrasonic fingerprint sensor

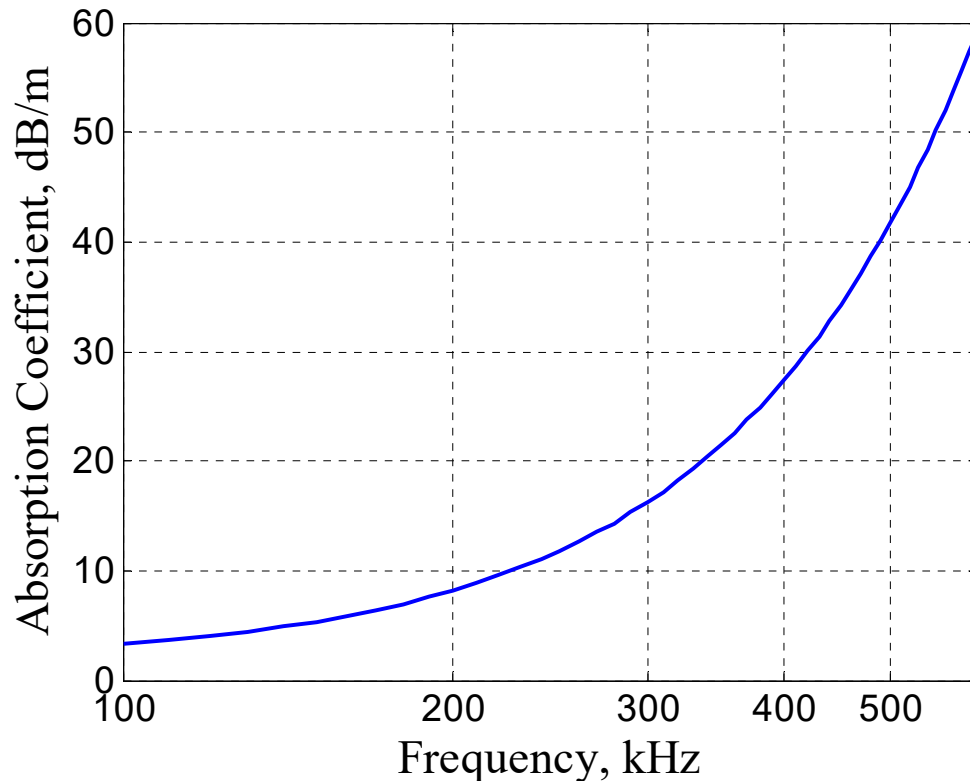
ToF Range Measurement: TX & RX Signals



ToF Range Measurement

- What frequency should be used?
- What determines the accuracy?

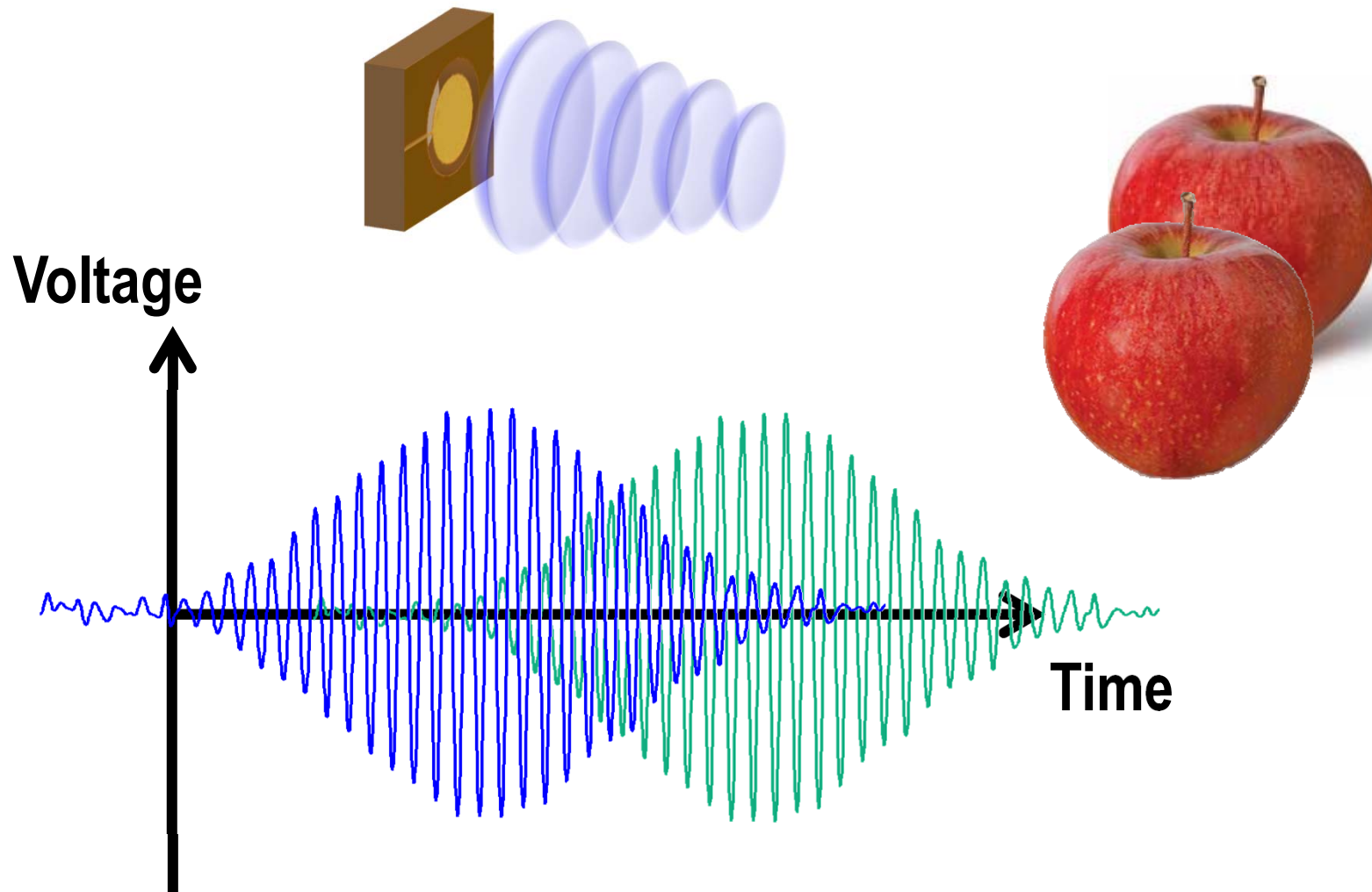
Air Absorption & Max Range Depend on Frequency



- Absorption loss:
 - 1 dB/m @ 40kHz
 - 10dB/m @ 200kHz
 - 100 dB/m @ 800kHz
- Pulse-echo range:
 - 10 m @ 40 kHz
 - 1 m @ 200 kHz
 - 10 cm @ 800 kHz

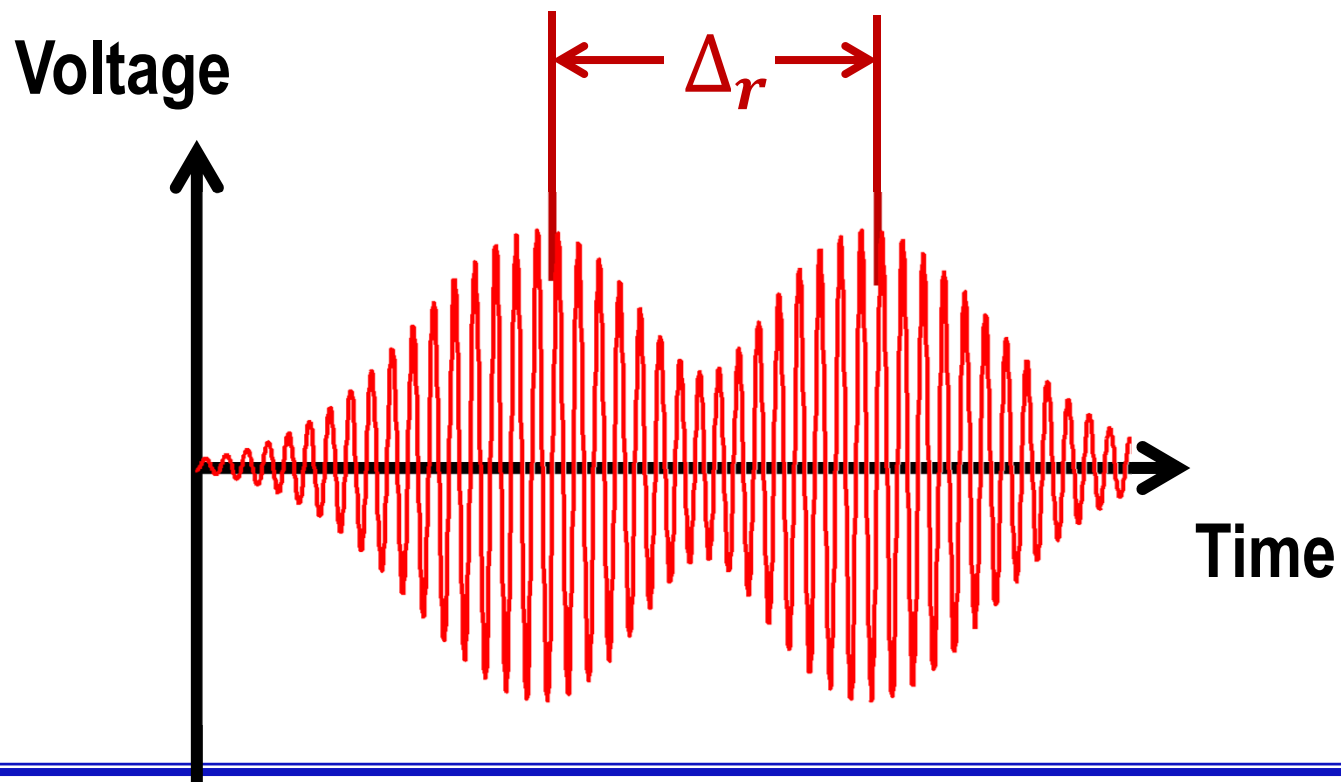
D.A. Horsley, R.J. Przybyla, M.H. Kline, S.E. Shelton, A. Guedes, O. Izyumin, and B.E. Boser,
IEEE MEMS 2016

BW determines axial resolution



BW determines axial resolution

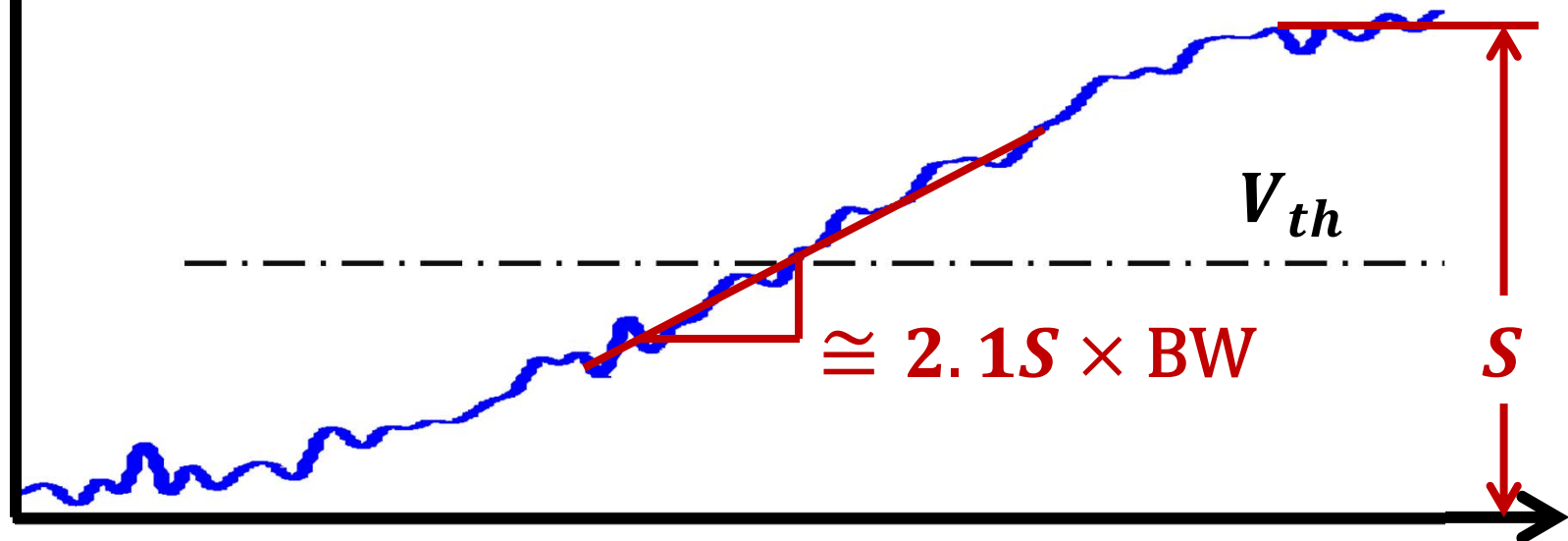
$$\Delta_r = \frac{c}{2} \left(T_p + \frac{0.27}{BW} \right) \cong \frac{c \cdot 0.77}{2 \cdot BW} \cong 1 \text{ cm}$$



BW & SNR determine accuracy

Magnitude

$$\sigma_r = \frac{c}{2BW} \frac{1}{2.1\sqrt{SNR}} \cong 0.5\text{mm @ } 500\text{mm}$$



Time

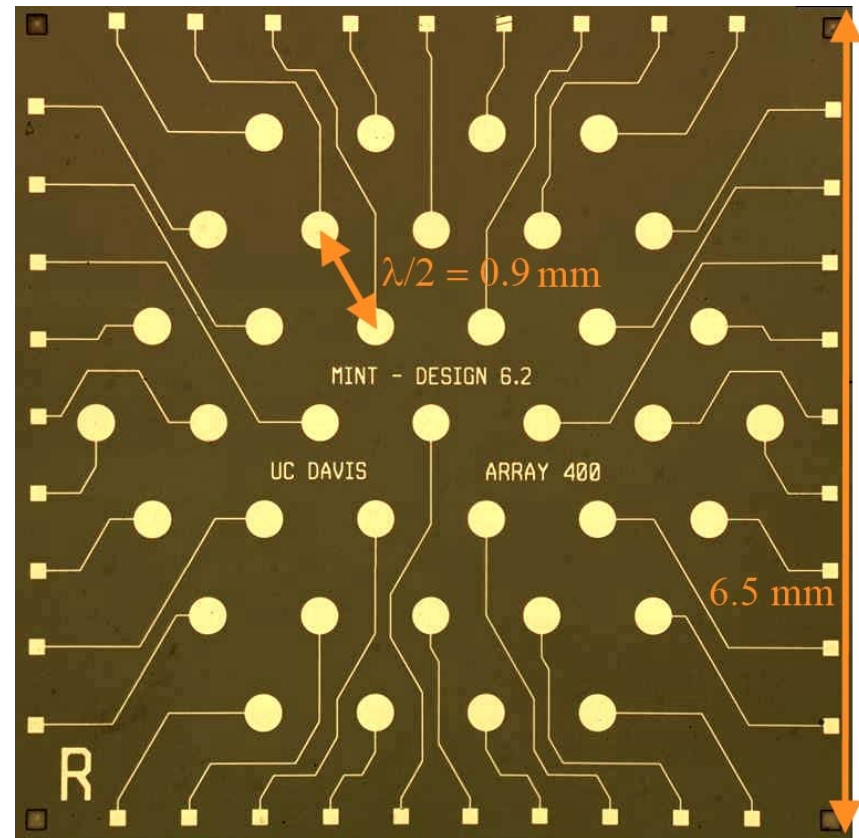
Outline

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- **Phased-array ultrasonics**
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Chip-Scale Phased Array

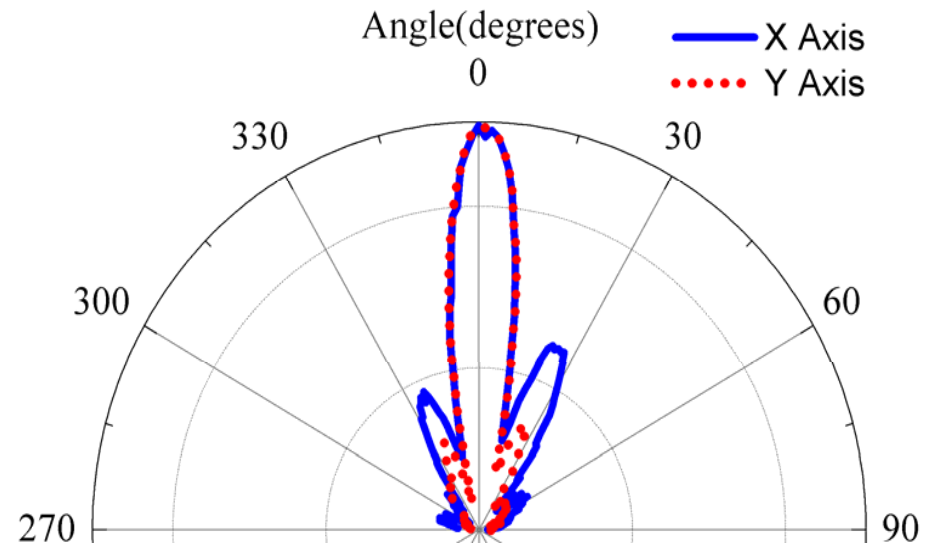
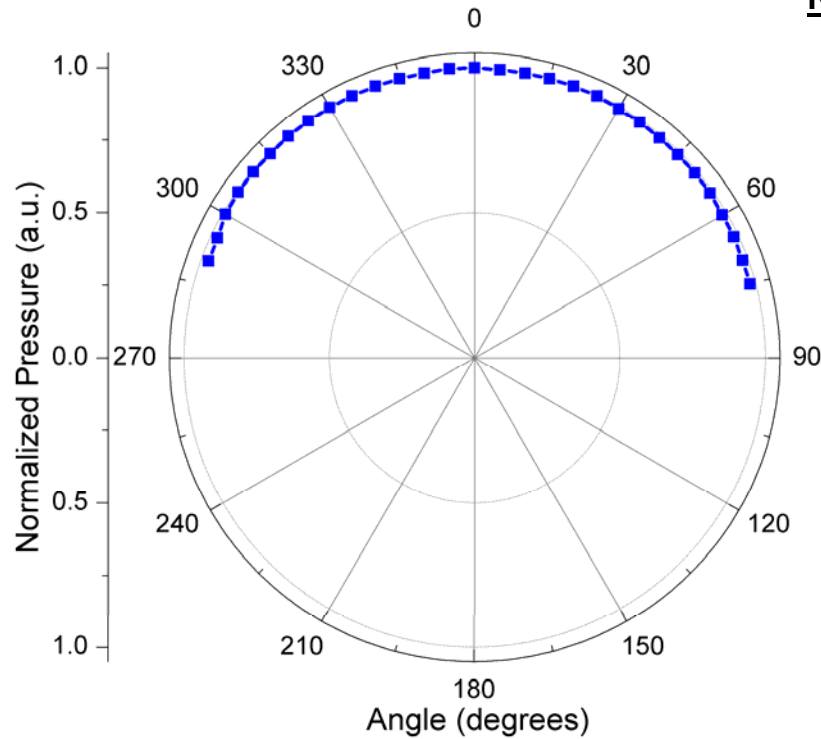
- 2D array of transducers:
 - Output power on-axis: N^2
 - Number of elements sets beam width
 - Beam width $\sim 180^\circ/N$ for linear array
 - Individual electrodes enable electrical beam steering
 - Spacing $\sim \lambda/2 = 0.9\text{mm}$ @ 200 kHz

37-Element Array



Phased Arrays are Directional

Narrow beam improves SNR & spatial resolution



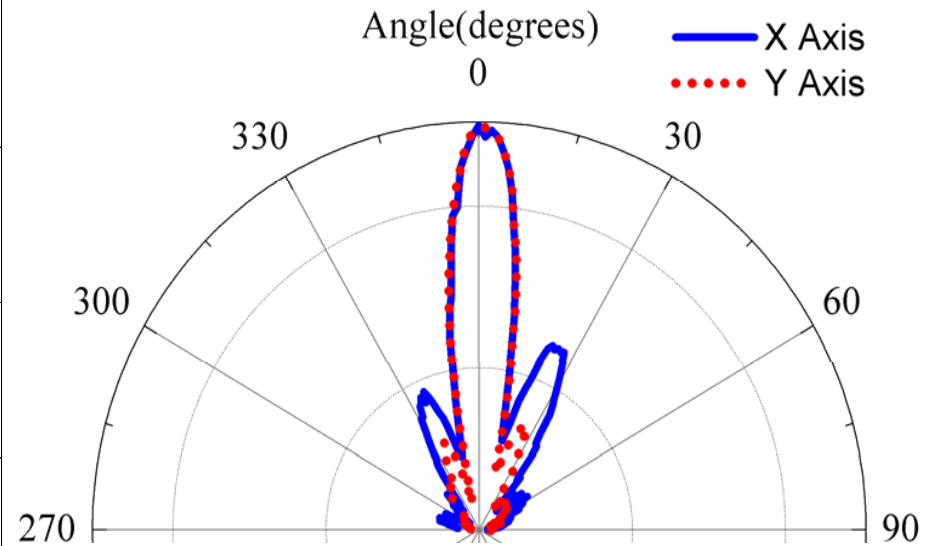
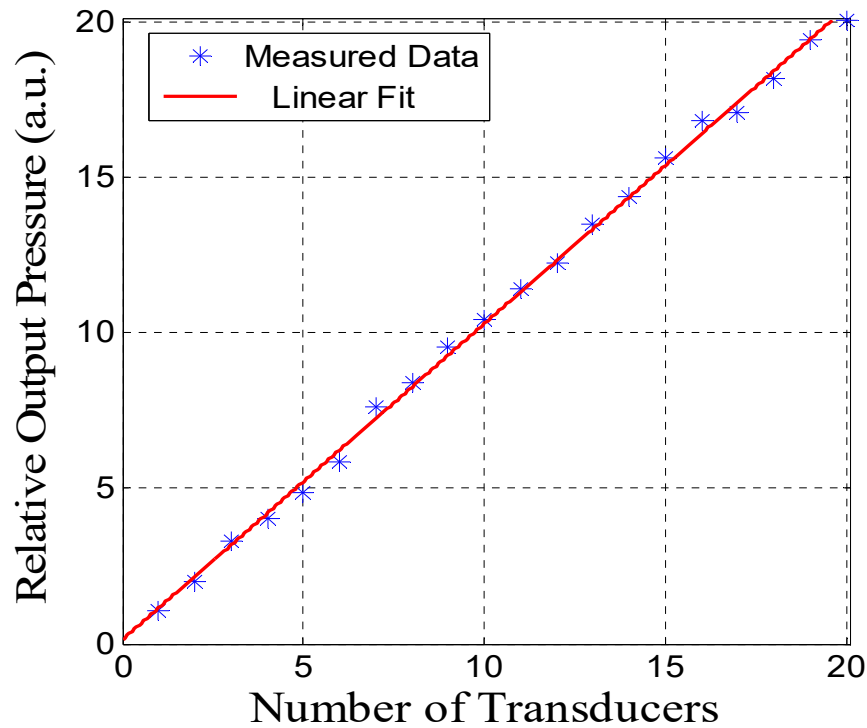
Single element

2D array

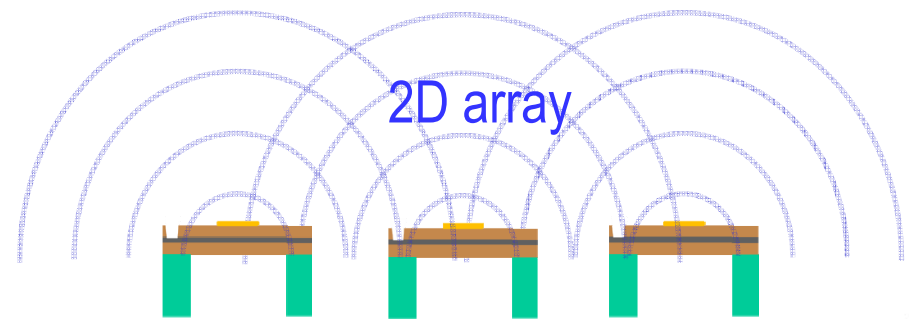
S. Shelton, A. Guedes, R. Przybyla, R. Krigel, B. Boser, D.A. Horsley, 2012 Solid-State Sensors Actuators & Microsystems Workshop, Hilton Head SC, June 2012.

Phased Arrays are Directional

Narrow beam improves SNR & spatial resolution



Output SPL Scales with N



S. Shelton, A. Guedes, R. Przybyla, R. Krigel, B. Boser, D.A. Horsley, 2012 Solid-State Sensors Actuators & Microsystems Workshop, Hilton Head SC, June 2012.

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- **Ultrasonic fingerprint sensor**

Ultrasonic Fingerprint Sensor

Qualcomm® Snapdragon Sense™

Go ahead, get your hands dirty.

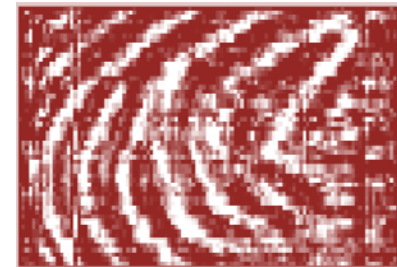
UC Davis, UC Berkeley, InvenSense

EE Times Connecting the Global
Electronics Community

News & Analysis

3-D Fingerprint Scanner Beats Apple's

Super-secure MEMS scanner may obsolete
passwords

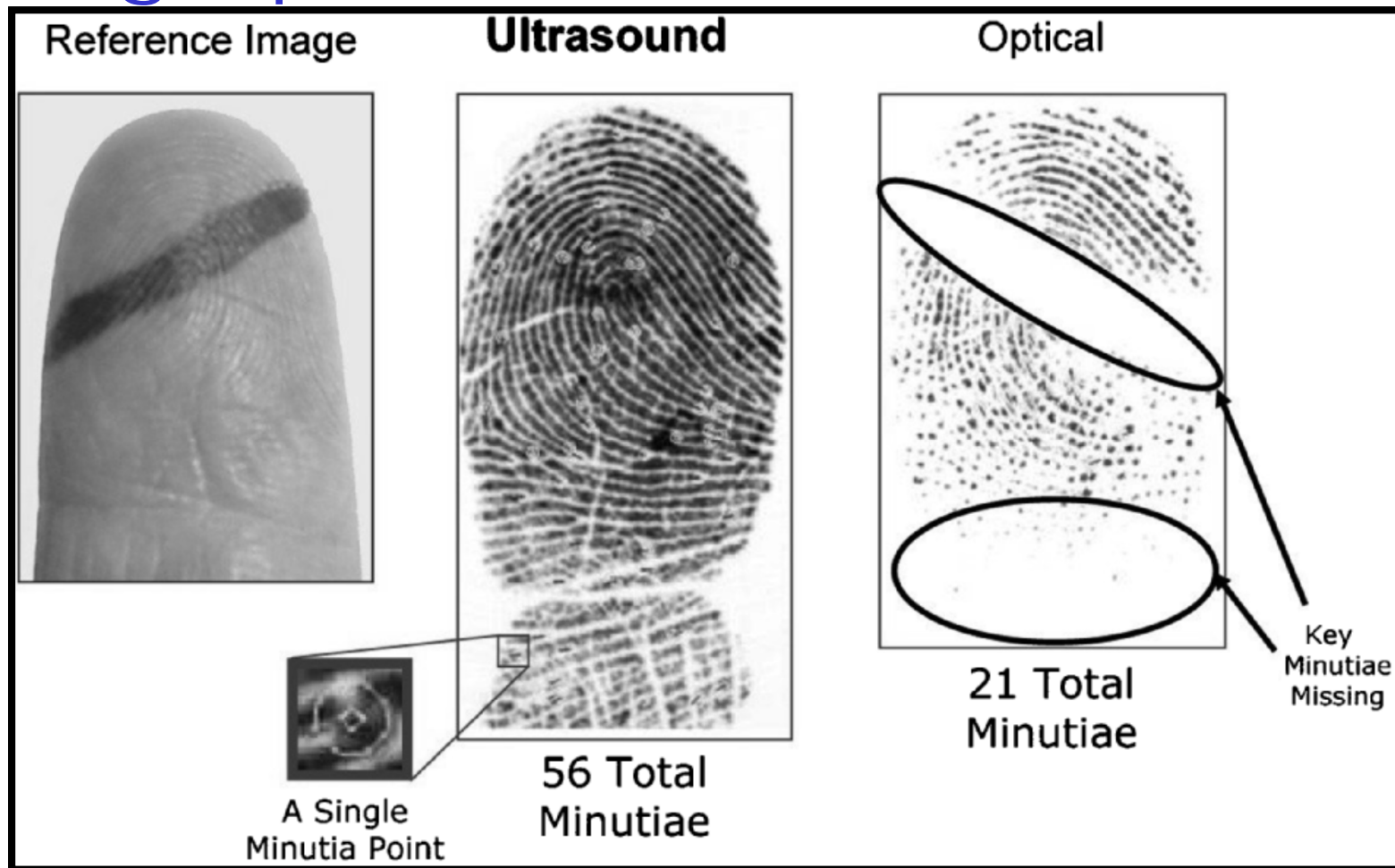


Jiang, et al, MEMS 2016

Tang, et al, ISSCC 2016

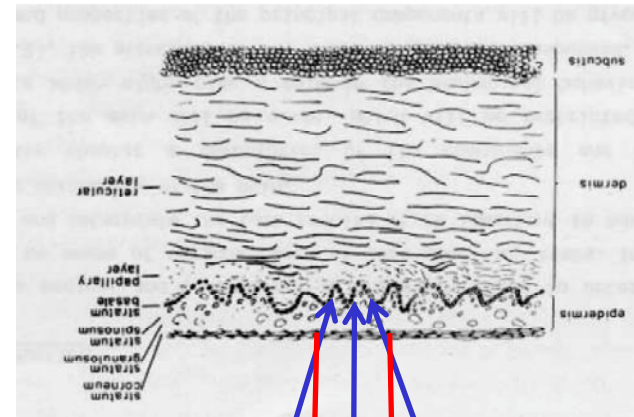
InvenSense® Announces UltraPrint™ Mass-
Manufacturable Ultrasound Fingerprint Touch Sensor
Solution

Ultrasound vs. Optical Fingerprint Sensor



J. K. Schneider, "Ultrasonic fingerprint sensors," in *Advances in Biometrics*. 2008

State of the art: Commercial Ultrasonic Fingerprint Sensor



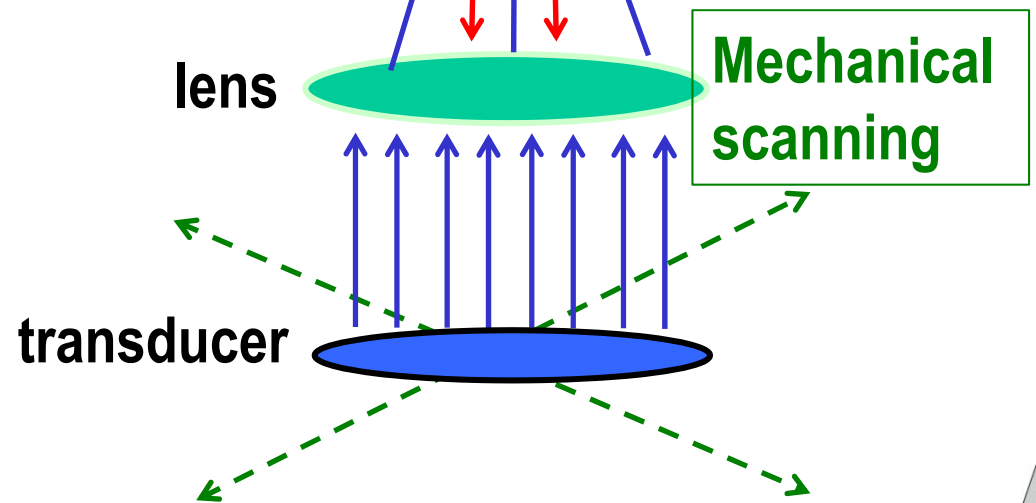
Pros:

→ Dermal detection

Cons:

→ Large system

→ mechanical scanning

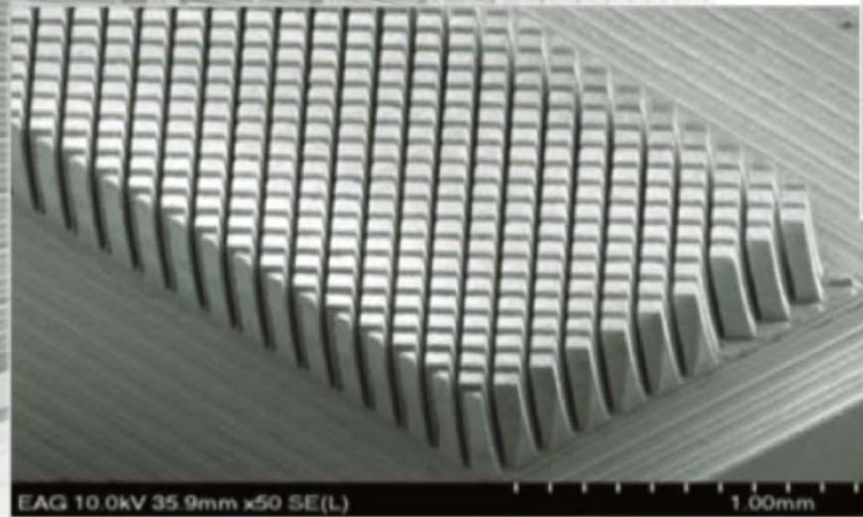


Reference: Ultra-scan®, U.S. patent 5224174

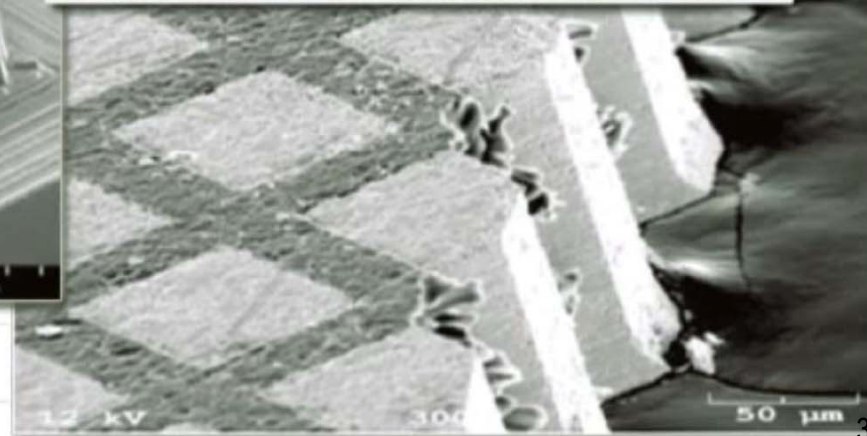
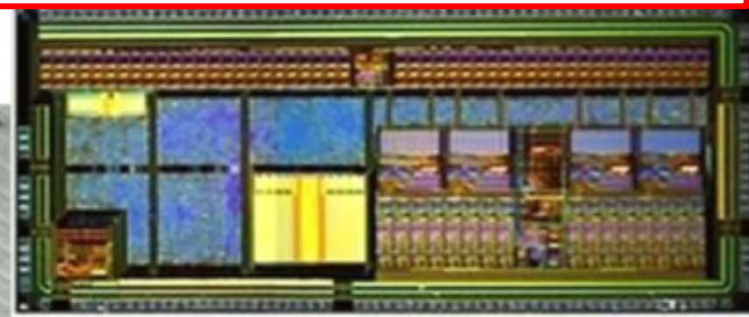
Bulk Piezo Fingerprint Sensors

Drawbacks:

- Interconnect is challenging
- Readout based on resonator Q (no advantage over capacitance)
- High manufacturing cost.

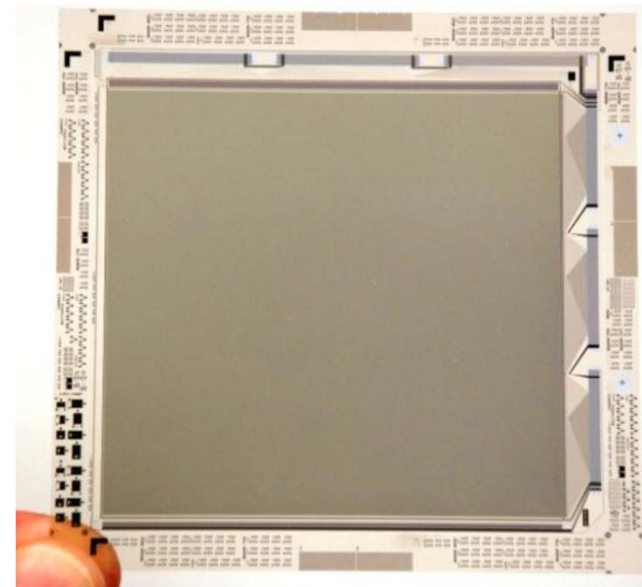


Sonavation Inc.



Qualcomm's Ultrasonic Fingerprint Sensor

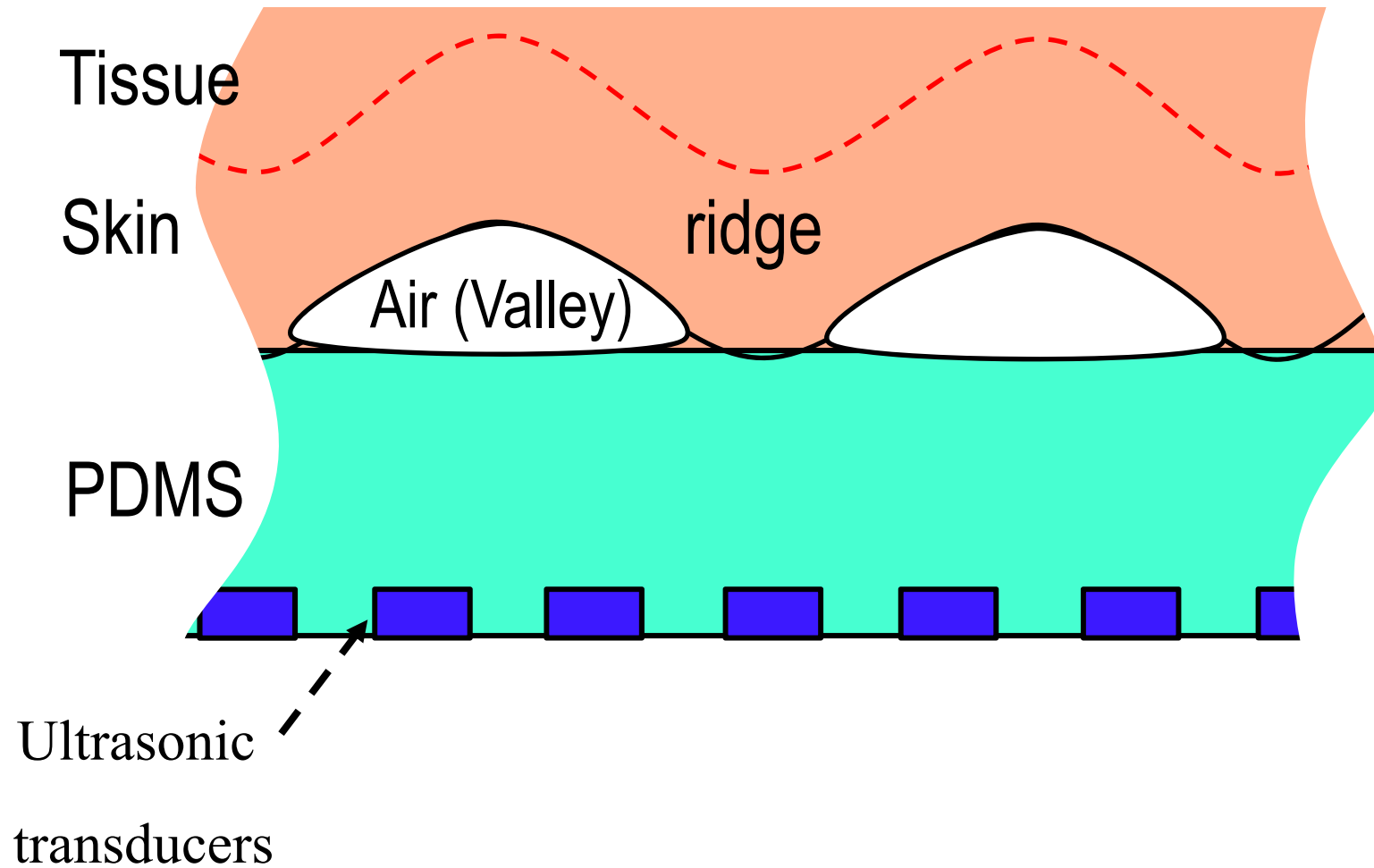
- TFT-based manufacturing
- 500 dpi
- Scalable to virtually any size
- Single-finger, four-finger, and full hand sensor.



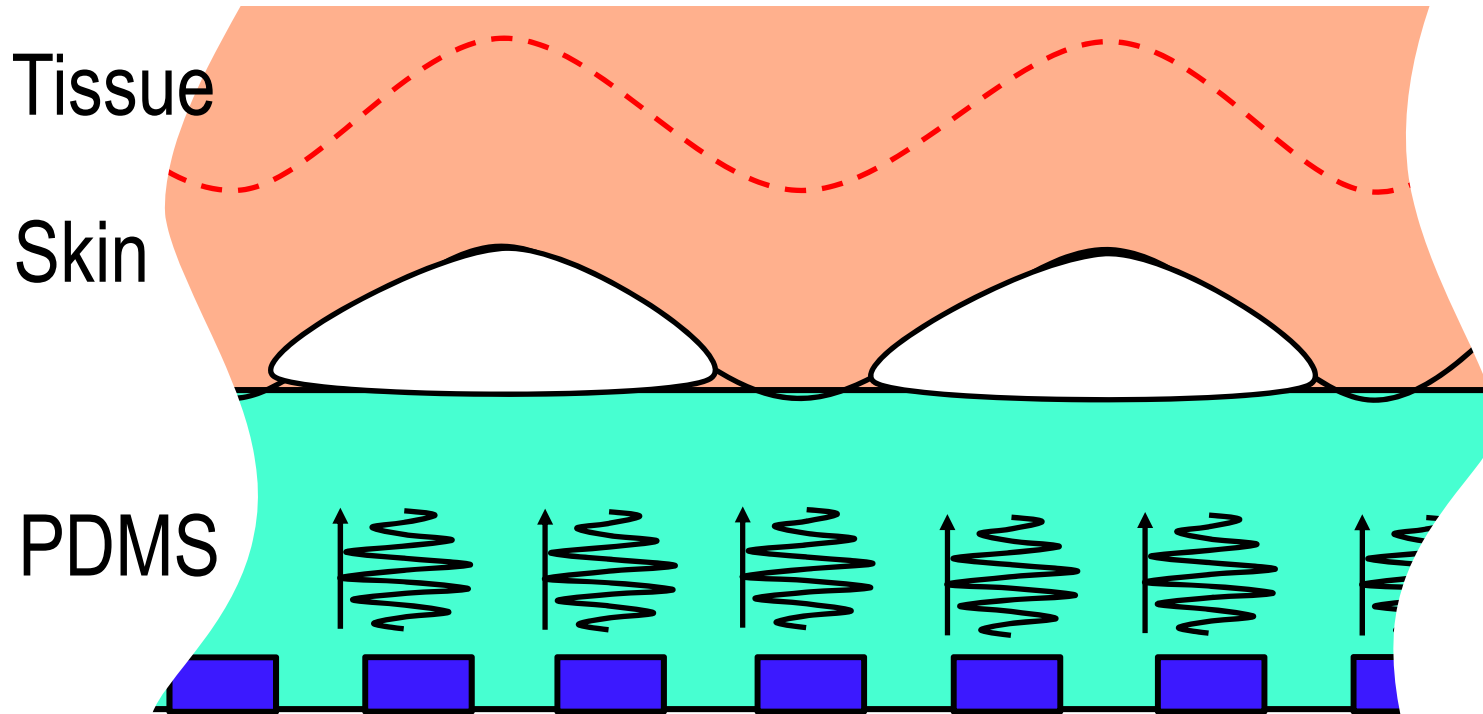
J. K. Schneider, "Biometrics Within the Wireless and Mobile Computing Industry," 2013

35

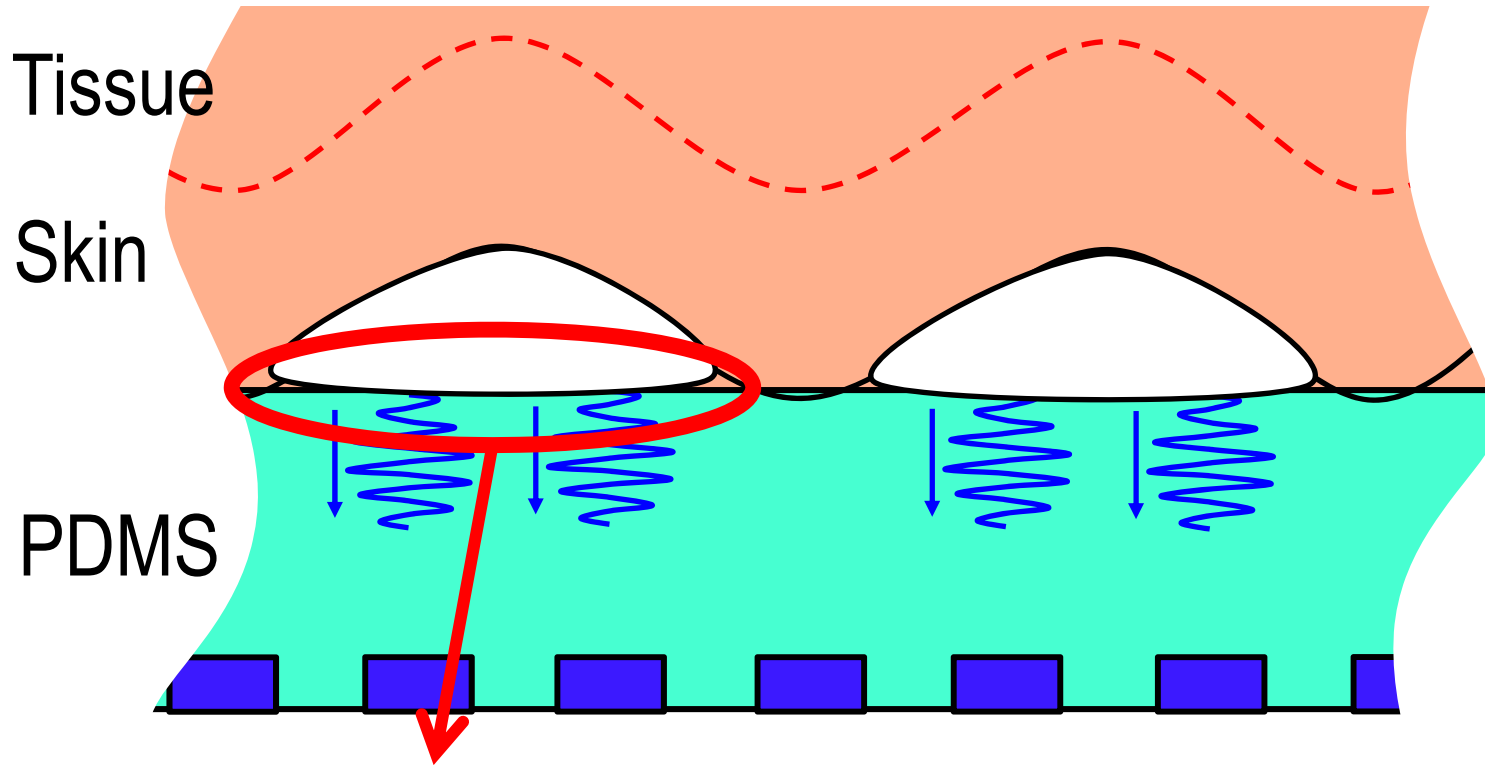
Operating Principle



Operating Principle

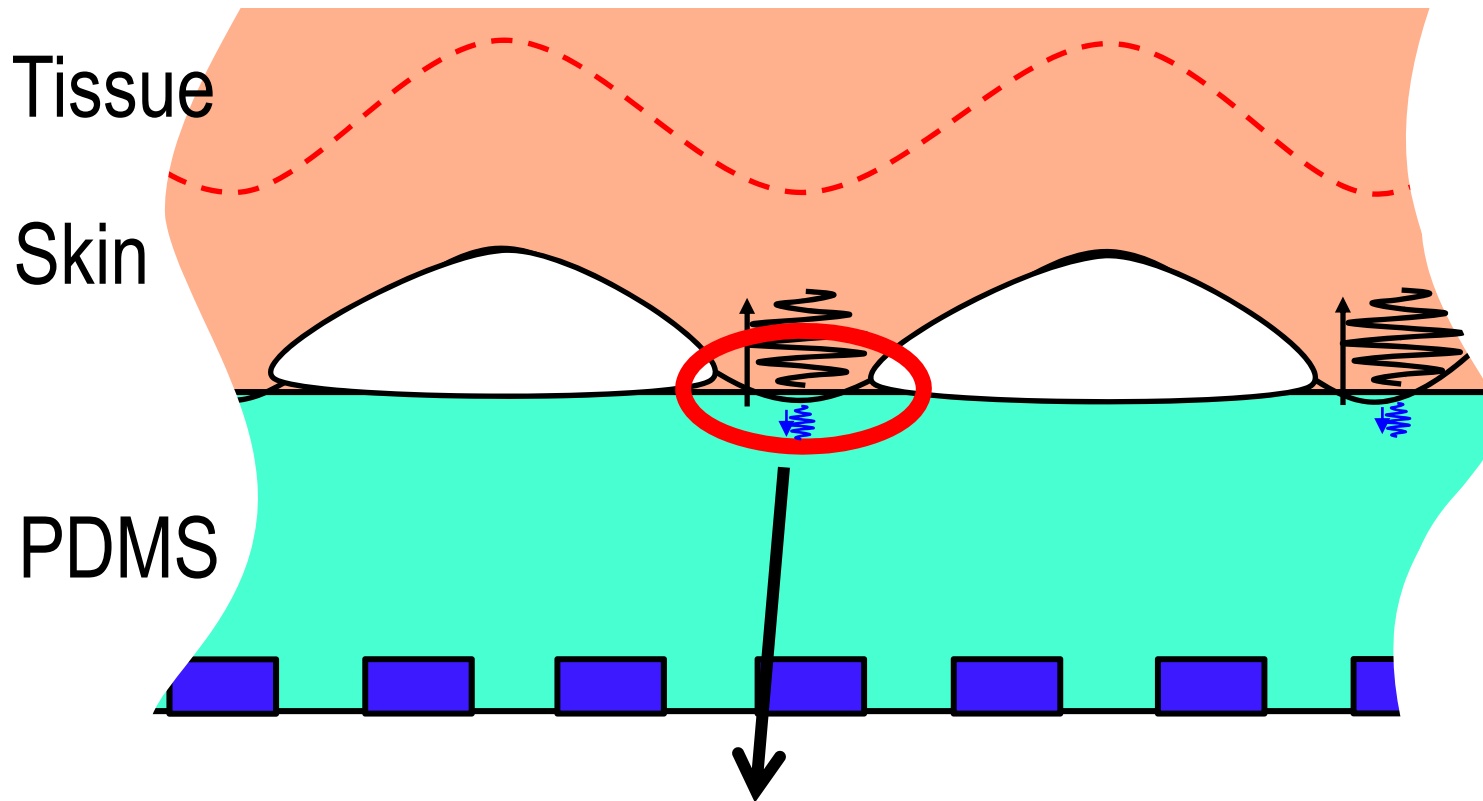


Operating Principle



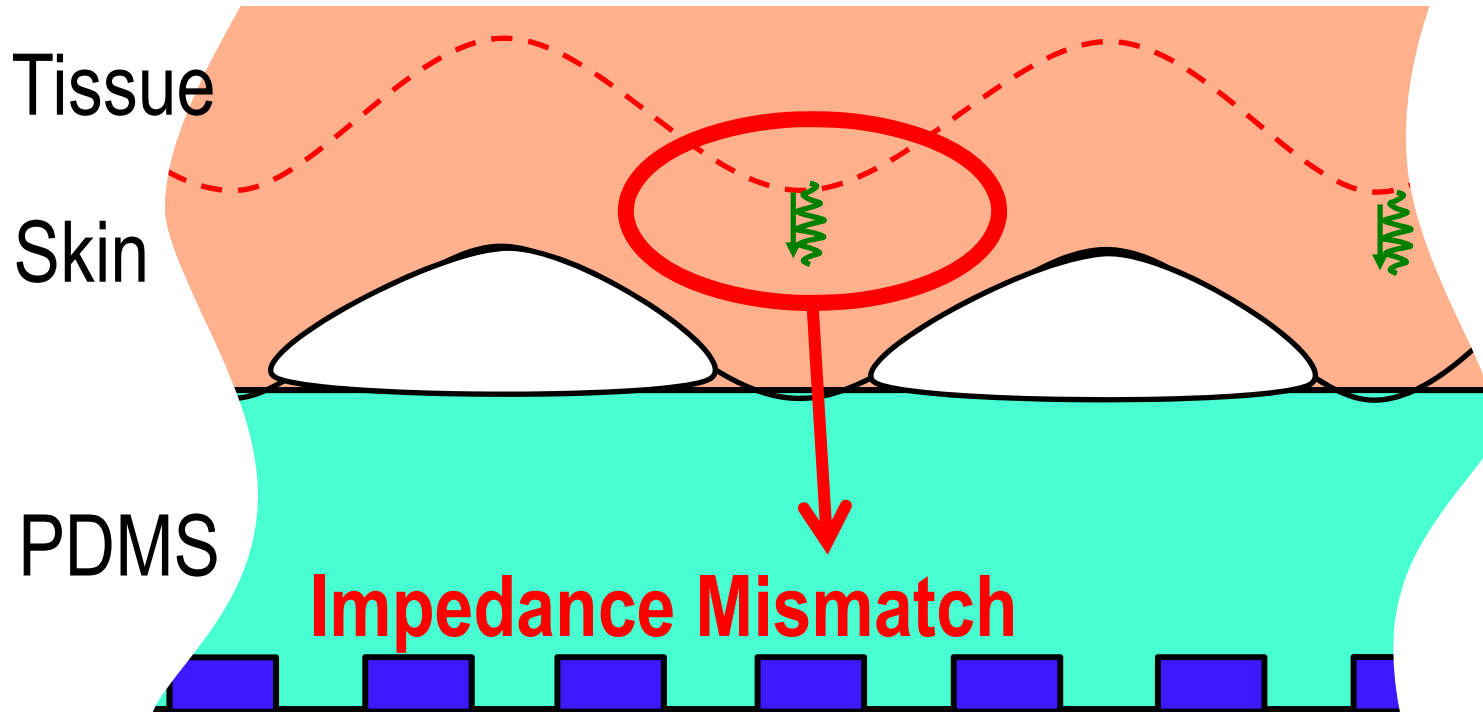
Huge Impedance Mismatch

Operating Principle

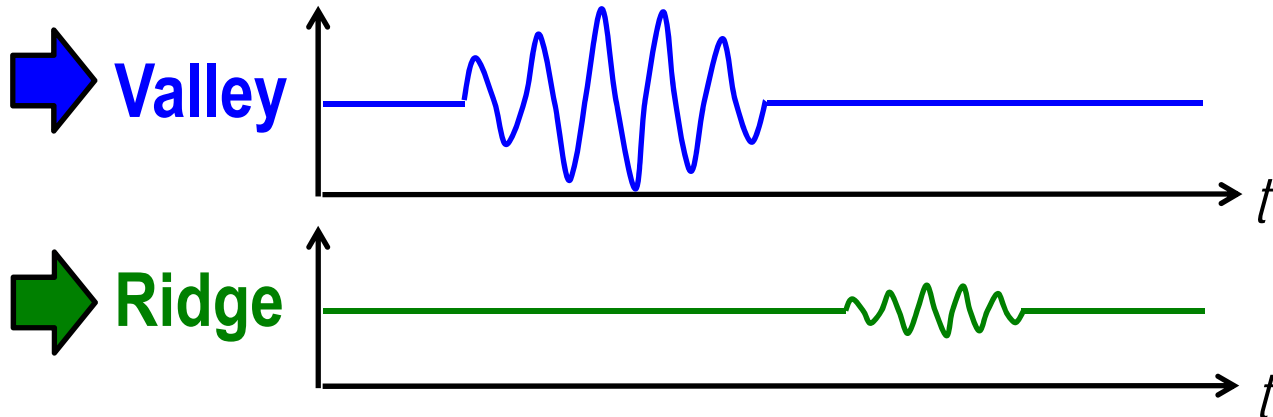
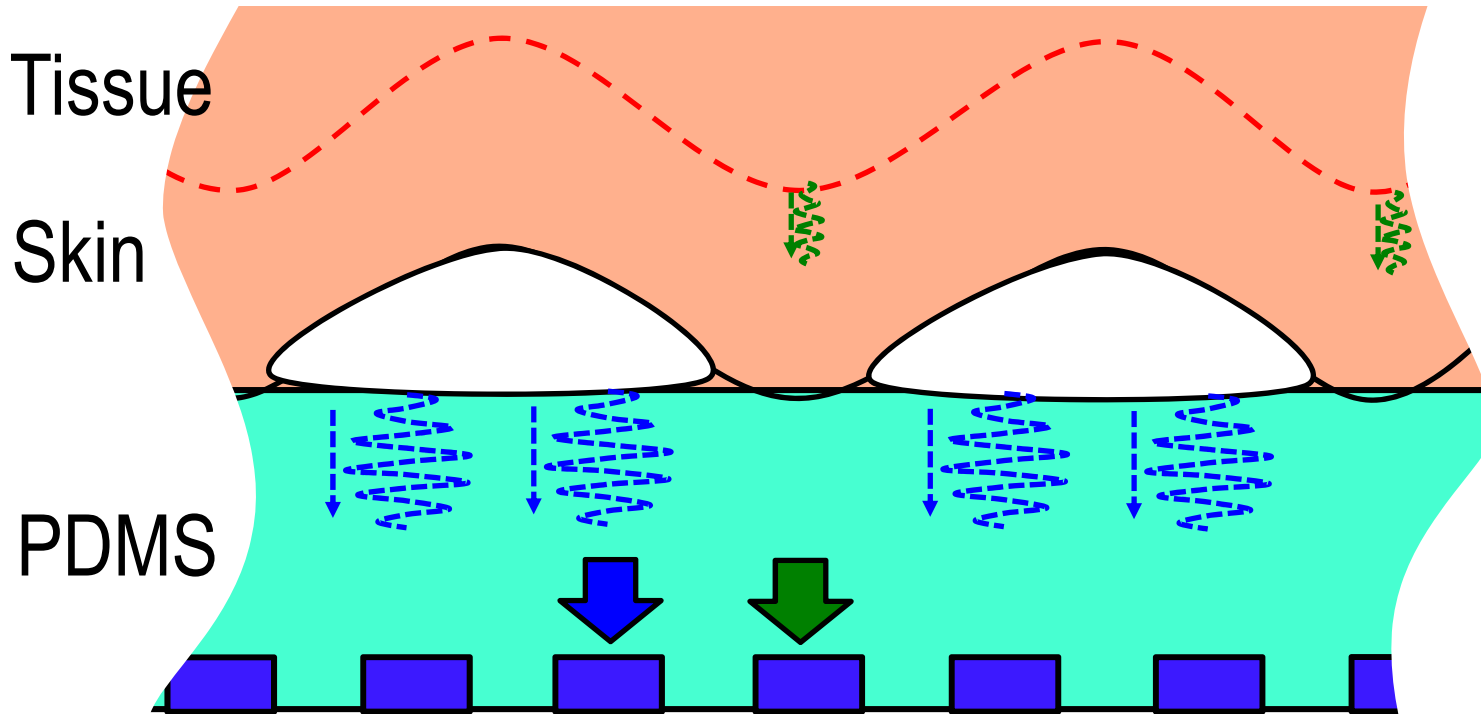


Impedance Match

Operating Principle



Operating Principle



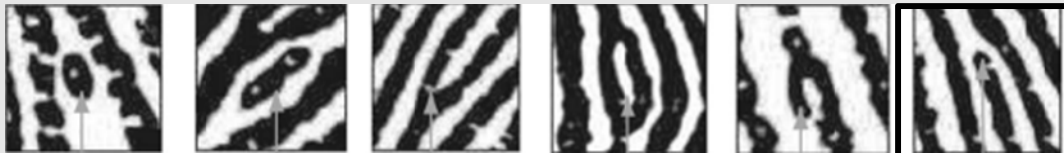
Fingerprint - Biometric Identity

Level 1 Features: Pattern



Left/Right/Double Loop

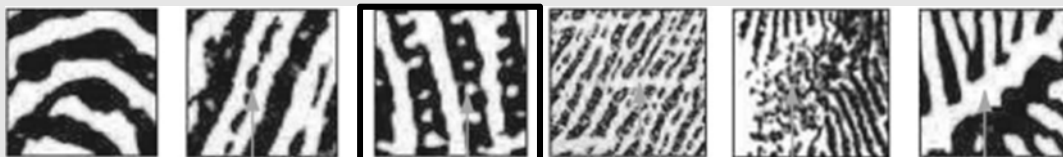
Level 2 Features: Minutia Points



FBI Standard 500 dpi

Ending

Level 3 Features



500+ dpi

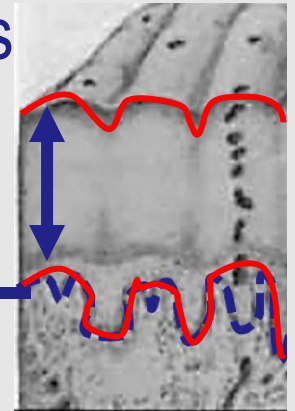
Pores

Jain, et al. IEEE, (2007)

Epidermis

~200 μm

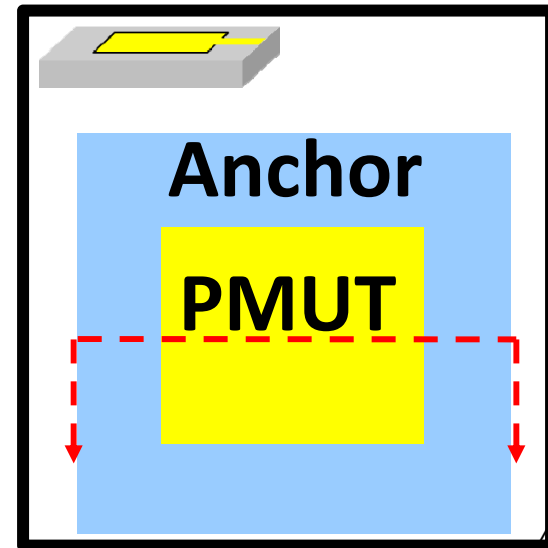
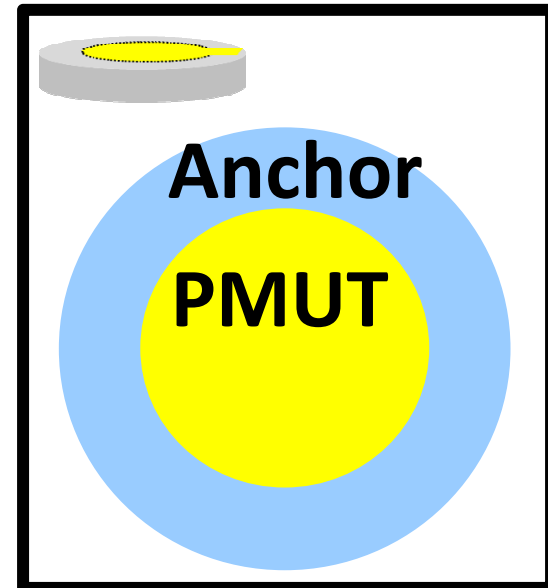
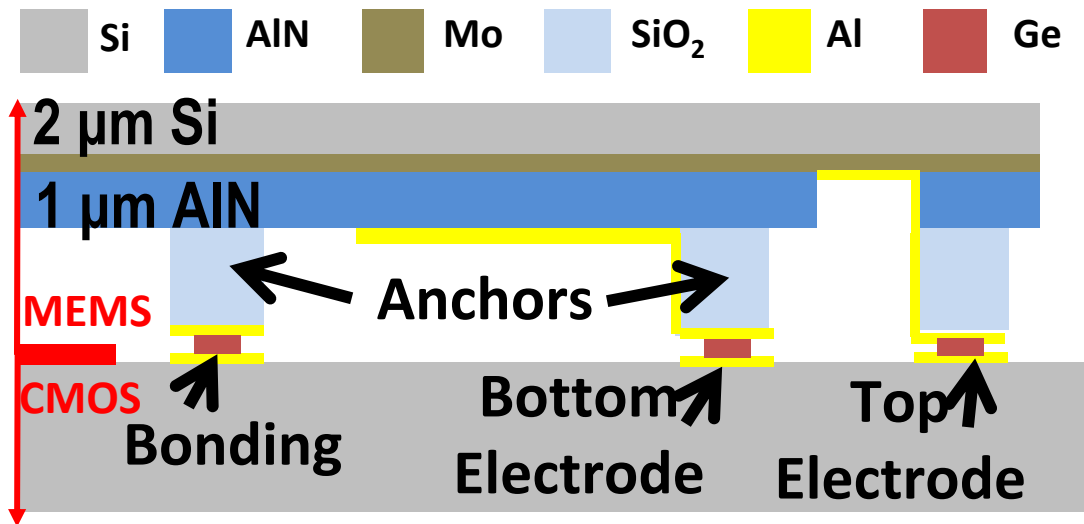
Dermis



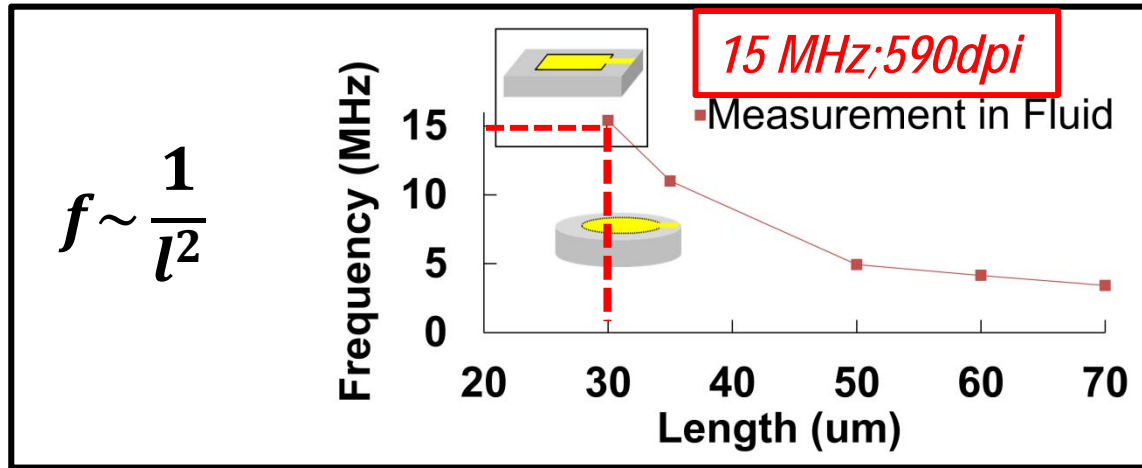
Sensor Resolution Requirement

| | |
|---------|-------------------|
| Lateral | 500 dpi |
| Axial | 200 μm |

PMUT Cross-Section

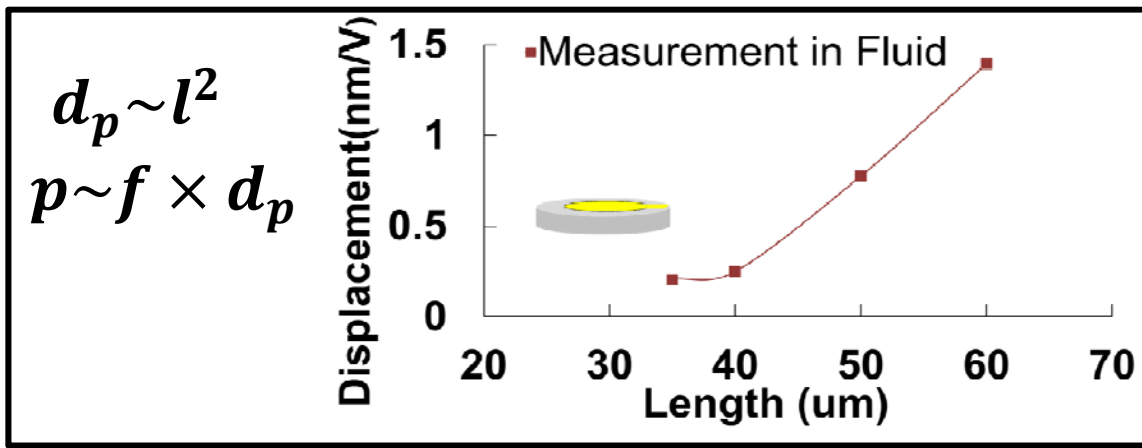


Individual PMUT Design



Length ↓ ➔ DPI ↑

Length ↓ ➔ Frequency ↑



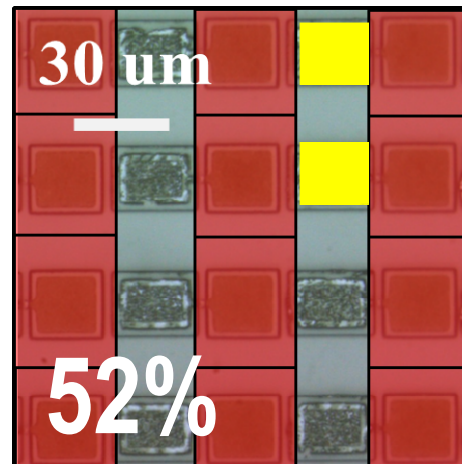
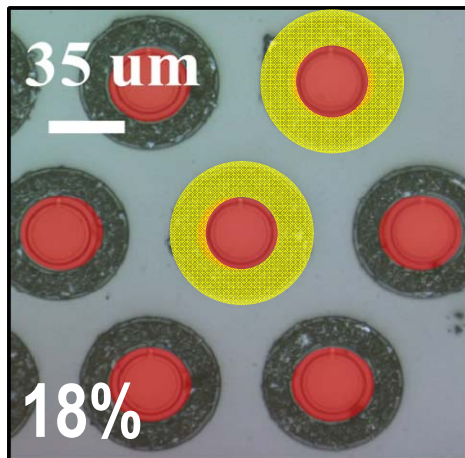
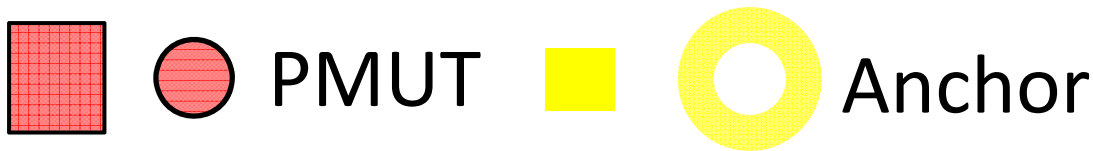
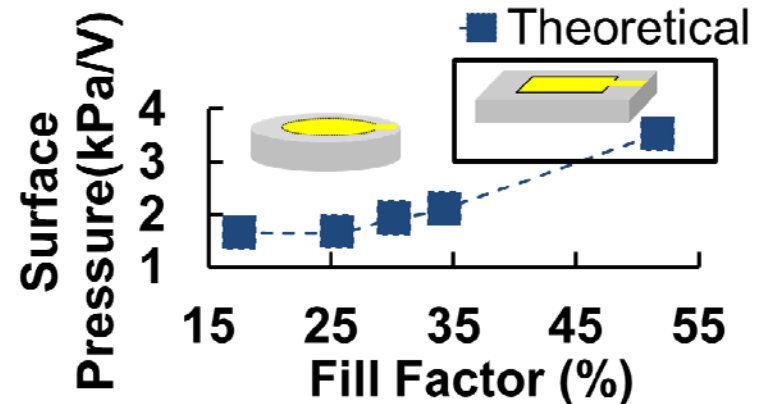
$p \sim A \sim l^2$

Length ↓ ➔ Pressure ↓

PMUT Array Design

$$p \sim \sqrt{FF}$$

$$\text{Fill Factor (FF)} \stackrel{\text{def}}{=} \frac{\text{PMUT Area}}{\text{Total Area}}$$

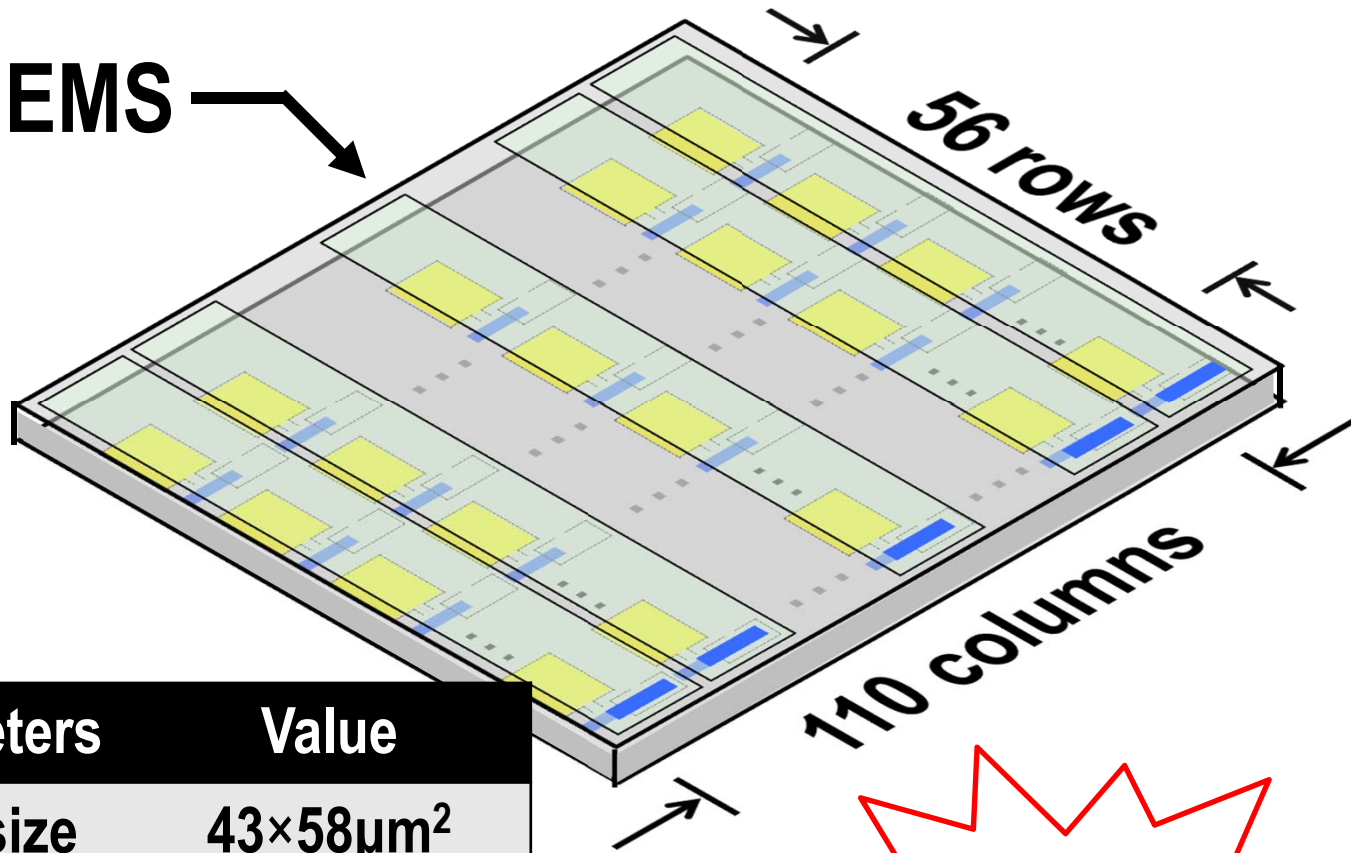


| Fill Factor | Pressure at 500 μm |
|-------------|-------------------------------|
| 18% | 1.6 kPa |
| 52% | 8.1 kPa |

X. Jiang et al, "Monolithic 591x438 DPI Ultrasonic Fingerprint Sensor," IEEE MEMS 2016.

Sensor Array

MEMS



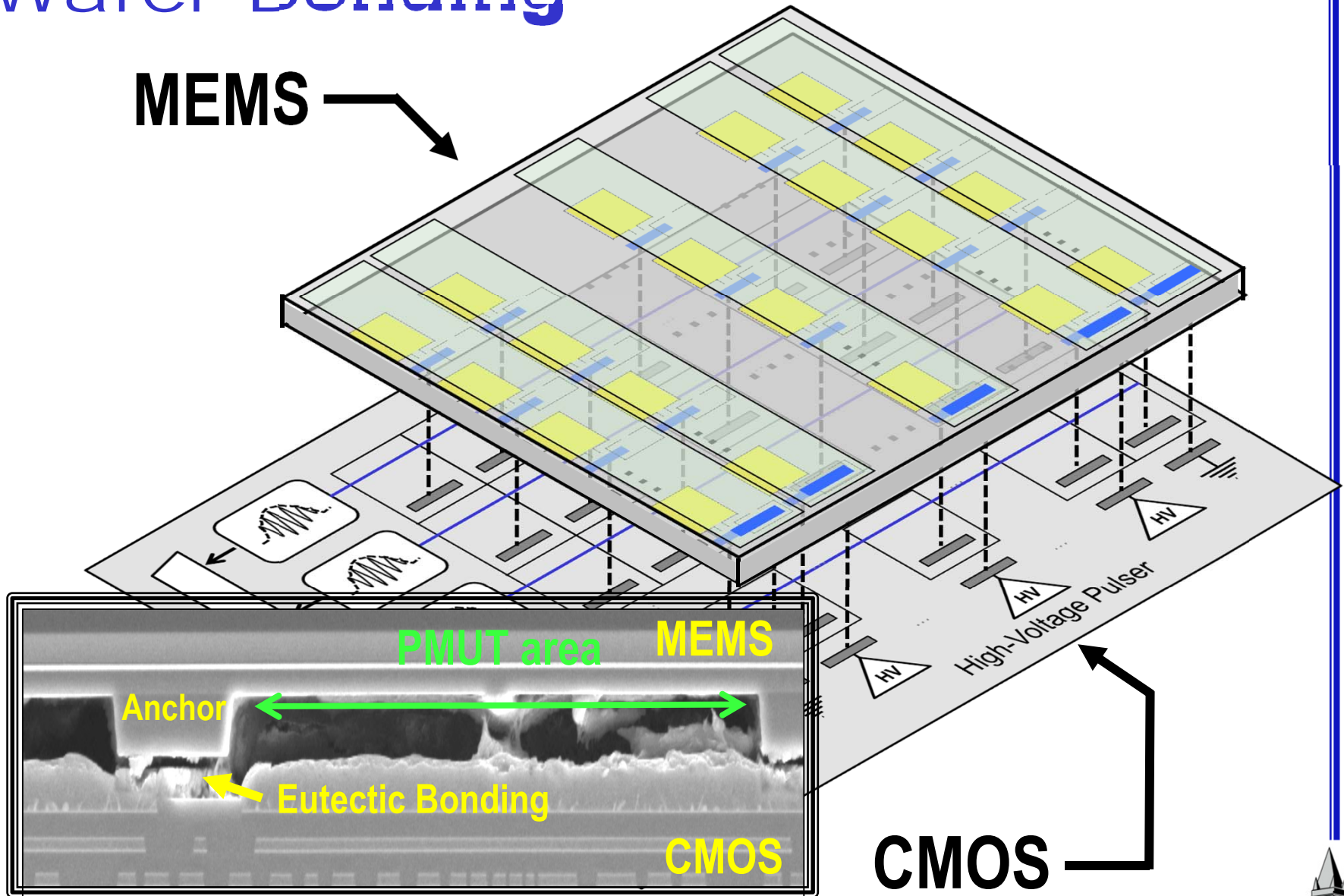
| Parameters | Value |
|-------------|-----------------------|
| Pixel size | 43×58 μm^2 |
| Resolution | 582×431 dpi |
| Fill-factor | 51.7% |

6160 pixels

H. Tang et al, "11.2 3D Ultrasonic Fingerprint Sensor on a Chip," 2016 ISSCC, pp. 202-203

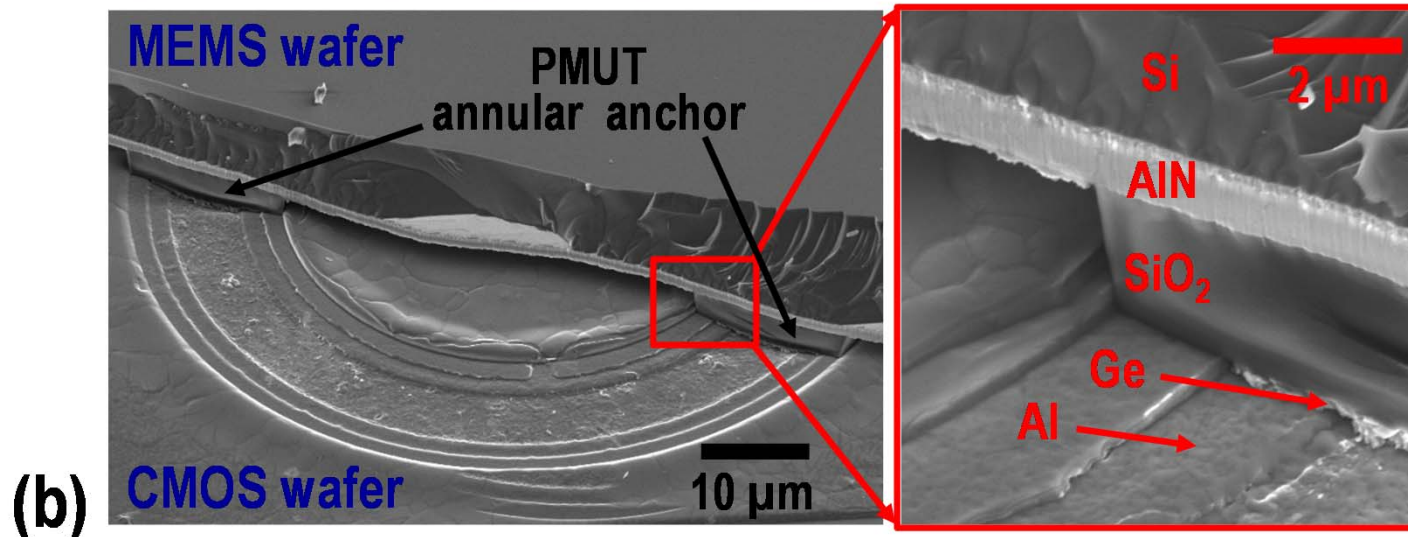
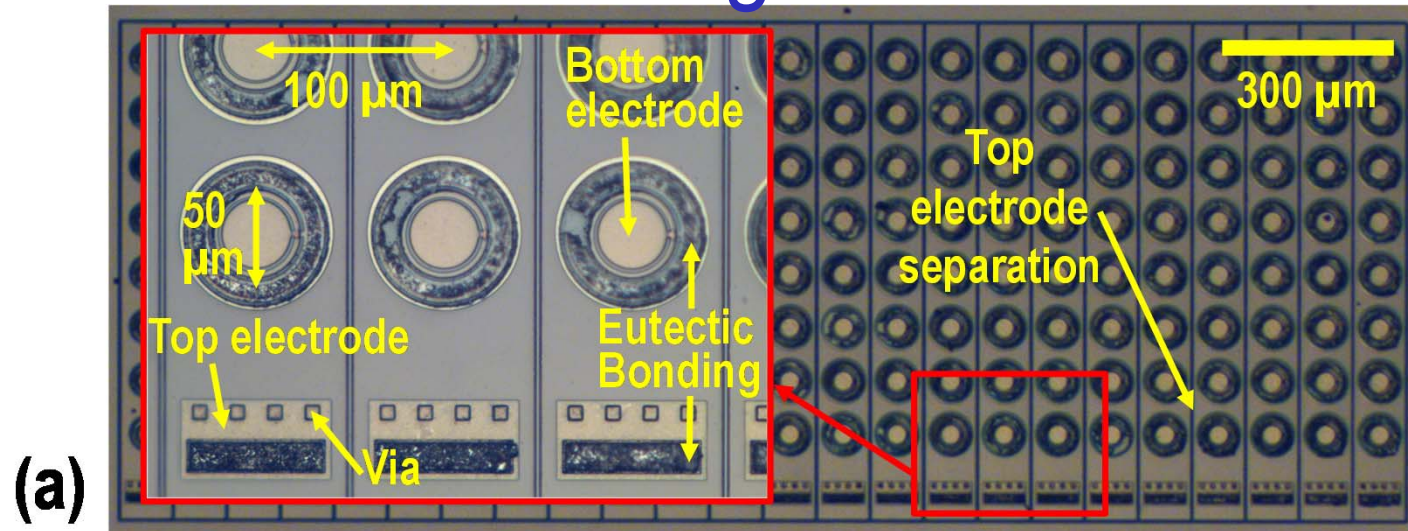
Wafer-Bonding

MEMS



CMOS

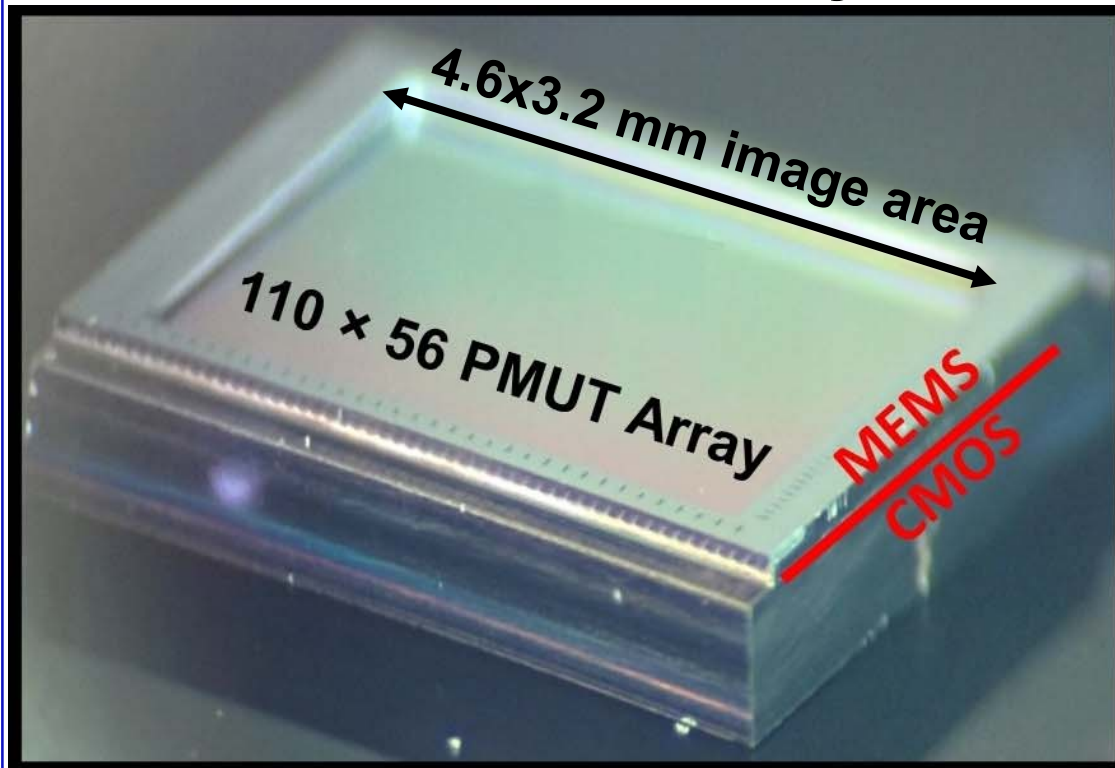
Optical and SEM Images



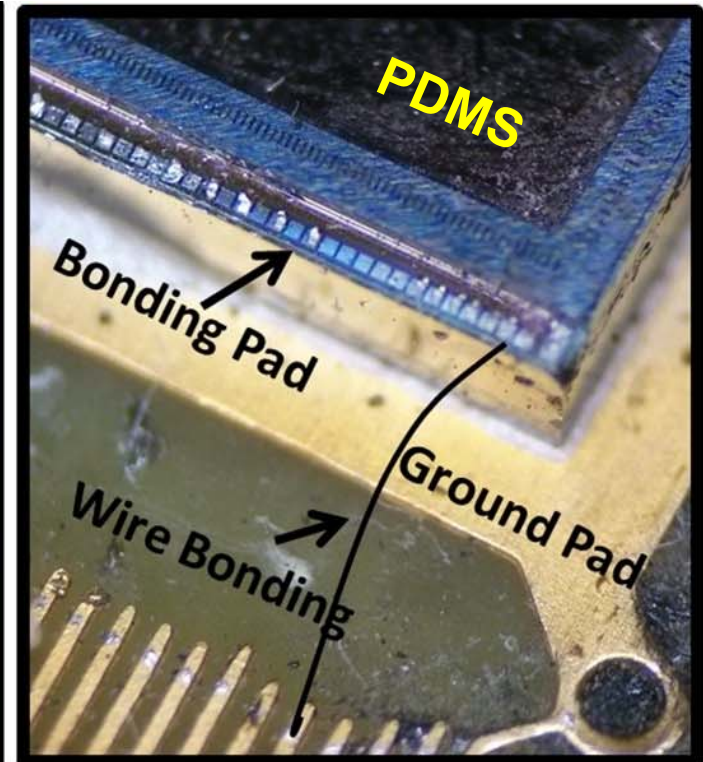
Y. Lu, et al, "Ultrasonic fingerprint sensor using a piezoelectric micromachined ultrasonic transducer array integrated with complementary metal oxide semiconductor electronics," APL , vol. 106, p. 263503, 2015

Sensor Die

Before Assembly



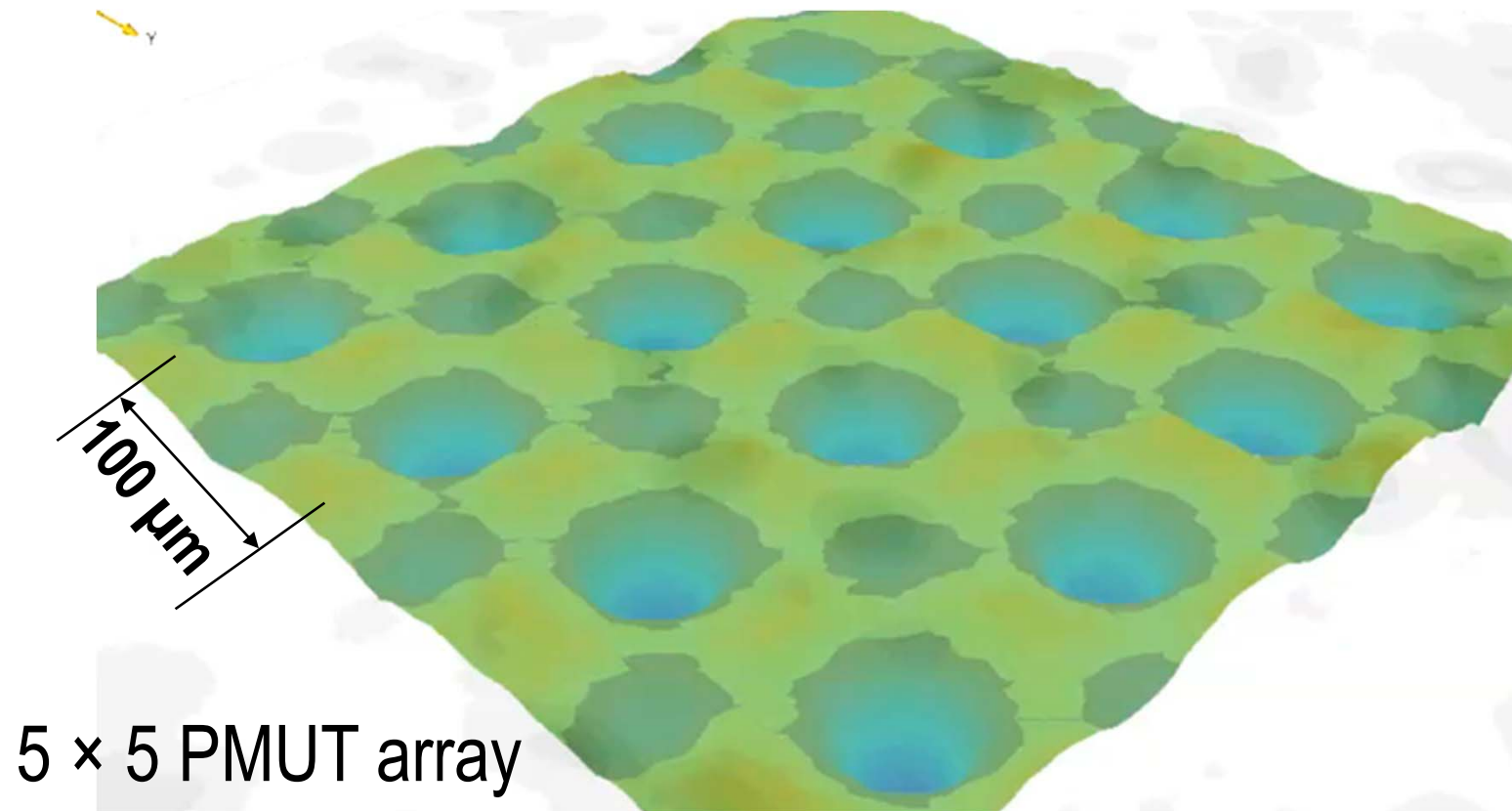
Assembled



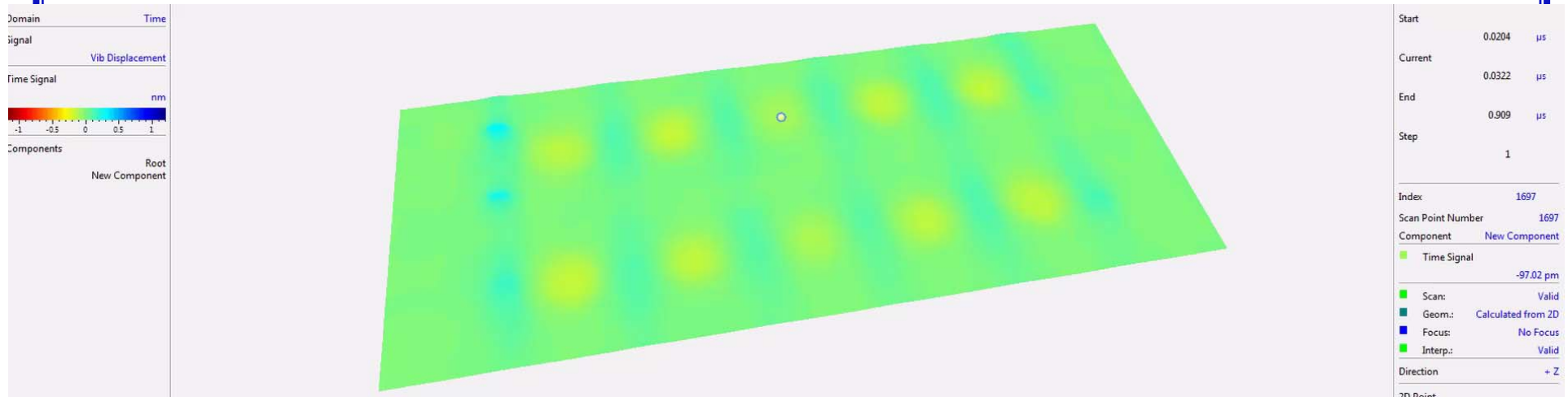
X. Jiang et al, "Monolithic 591x438 DPI ultrasonic fingerprint sensor" IEEE MEMS 2016, pp. 107-110.

J.M. Tsai, et al, "Versatile CMOS-MEMS integrated piezoelectric platform", *Transducers* 2015, pp. 2248-2251

PMUT motion at 28 MHz captured via LDV



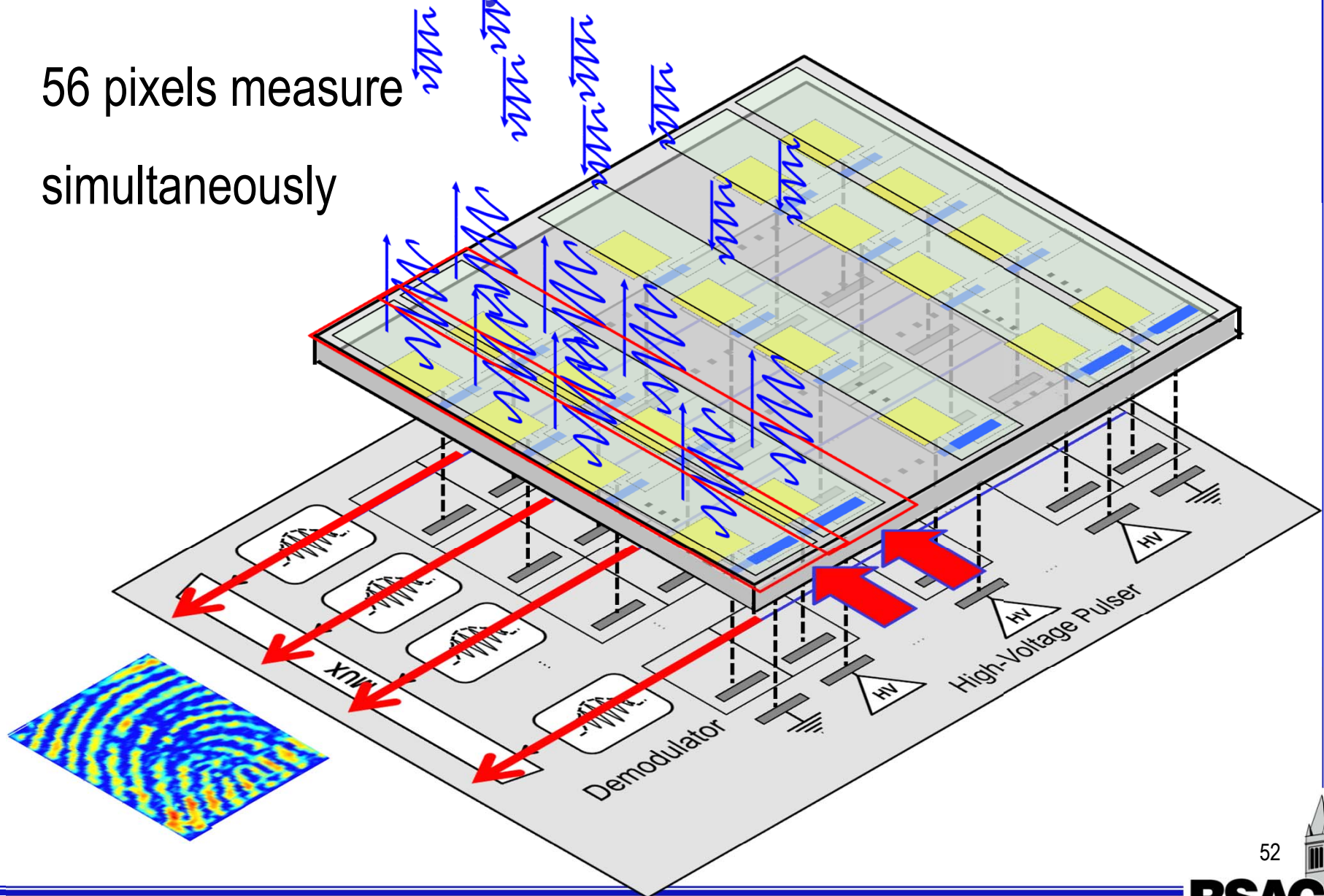
TX Pulse Dynamics



- Imaged through PDMS coupling layer
- 5 columns excited with 2-cycle 14 MHz pulse
- Antiphase motion can be seen between PMUTs

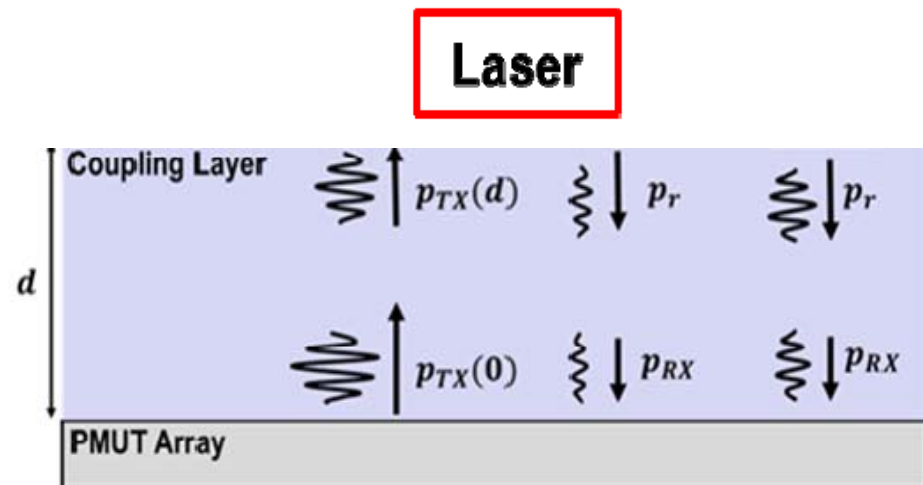
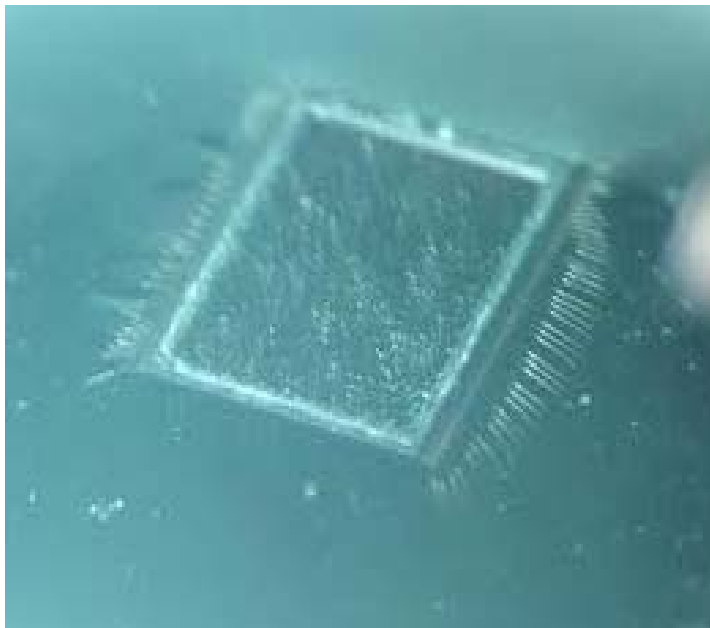
Measurement Cycle

56 pixels measure
simultaneously



Pressure Field Images

- Ultrasonic pressure field at the PDMS coupling layer surface is imaged using a scanning LDV



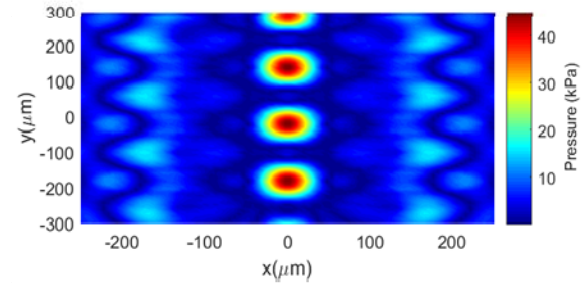
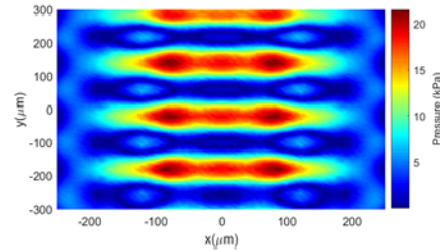
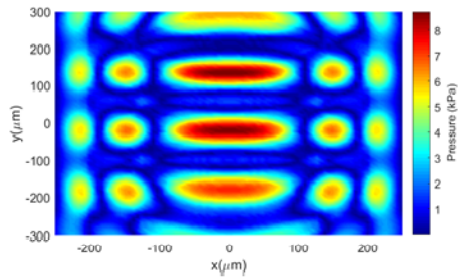
Pressure Field Images

1 Col

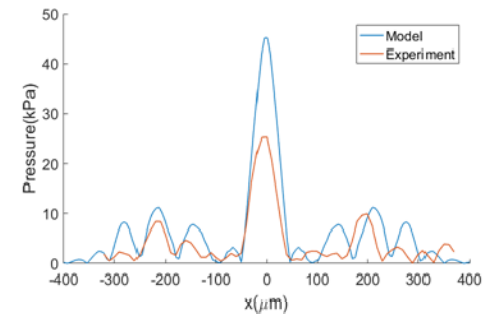
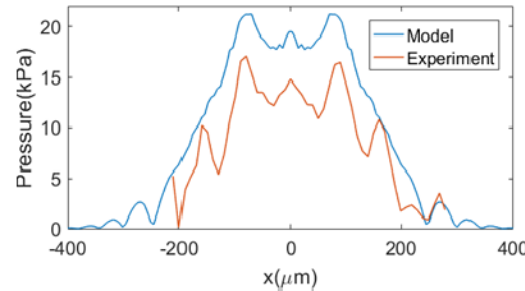
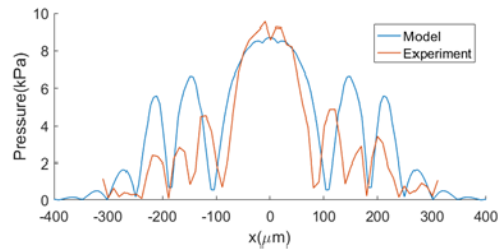
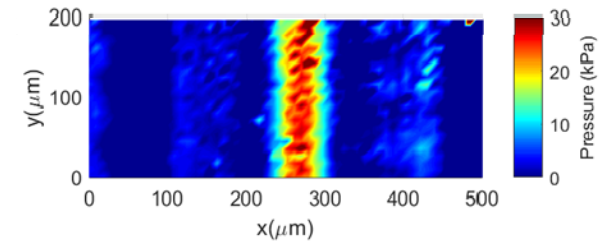
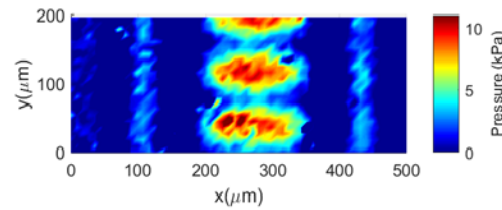
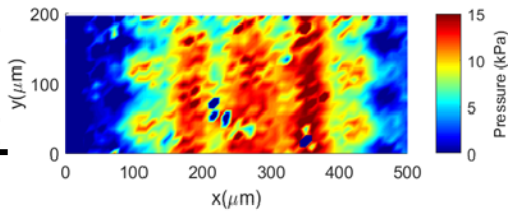
5 Col

5 Col Beamform

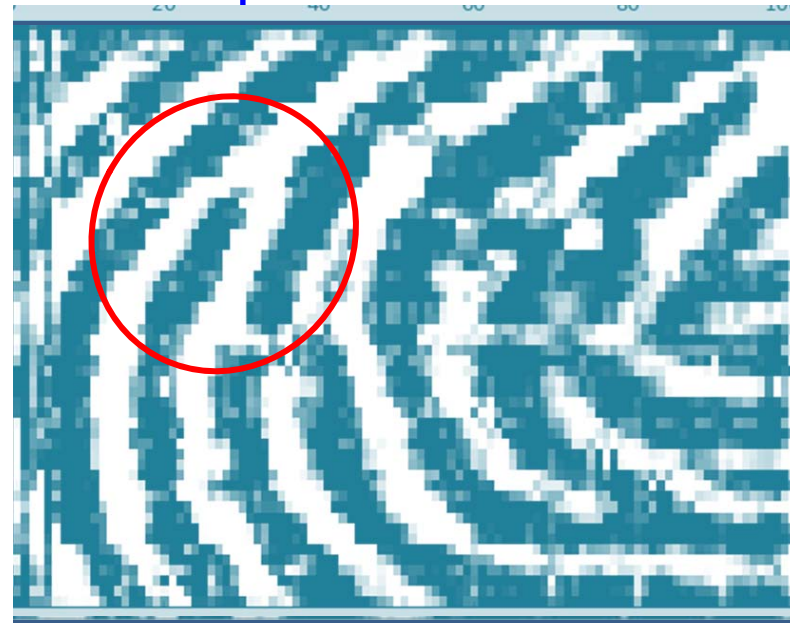
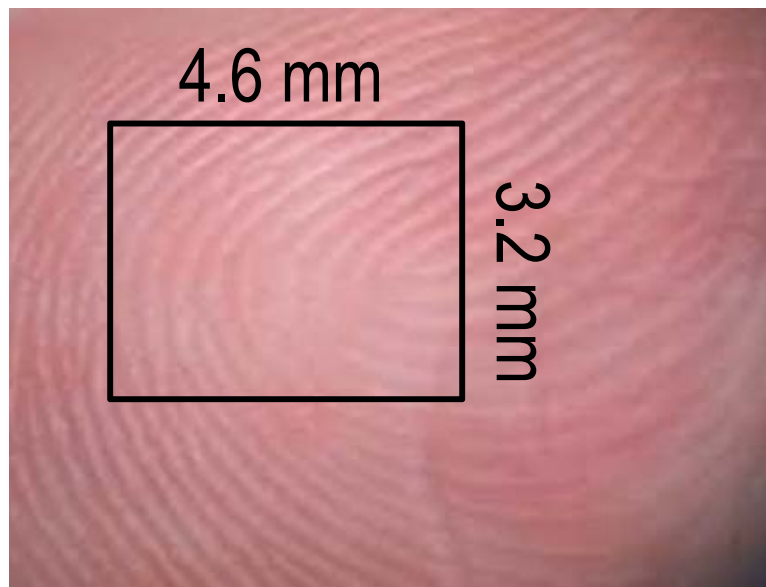
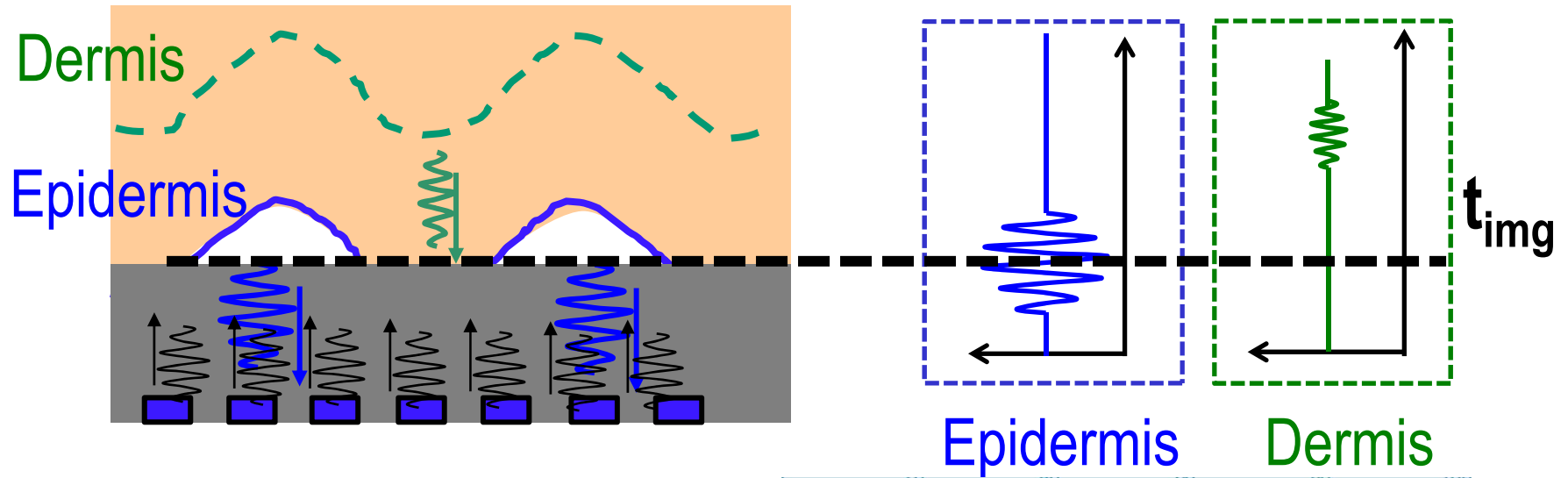
Model



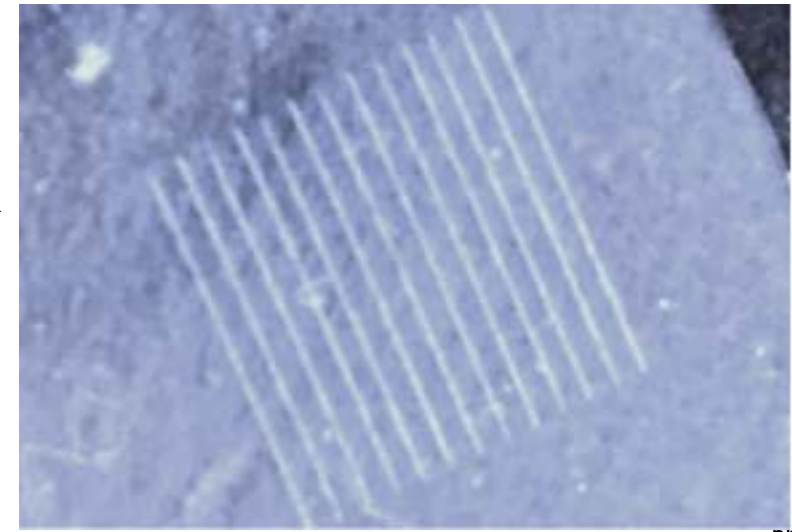
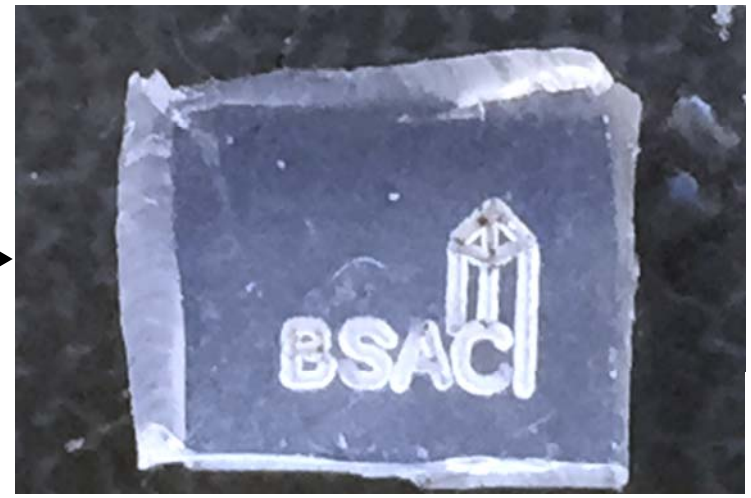
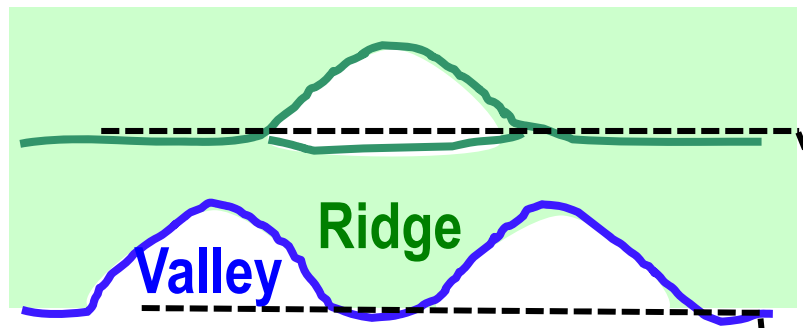
Experiment



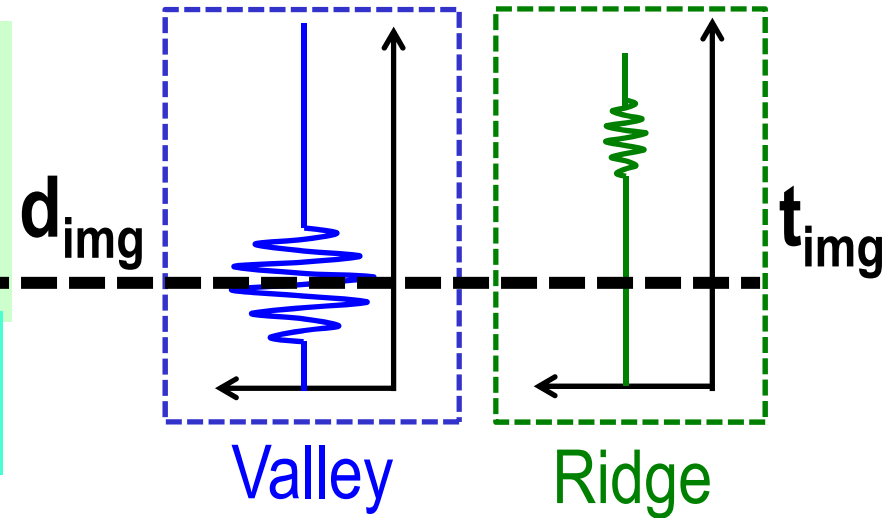
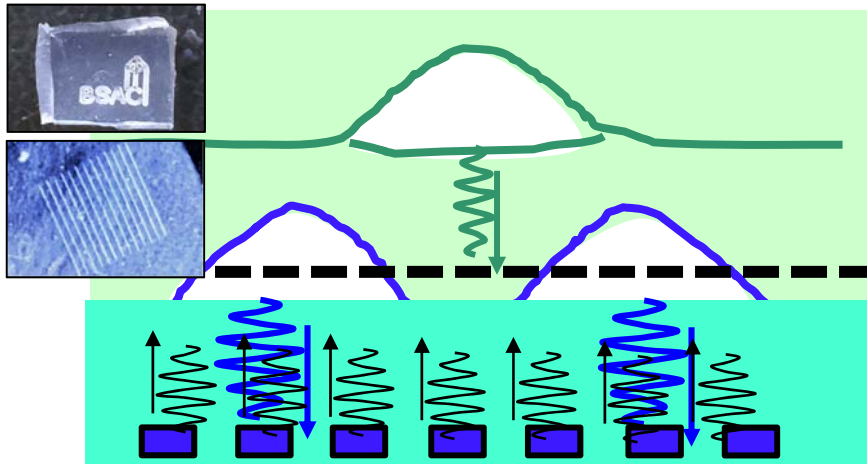
Pulse Echo Fingerprint Image



Multi-Layer Phantom



Multi-Layer Phantom

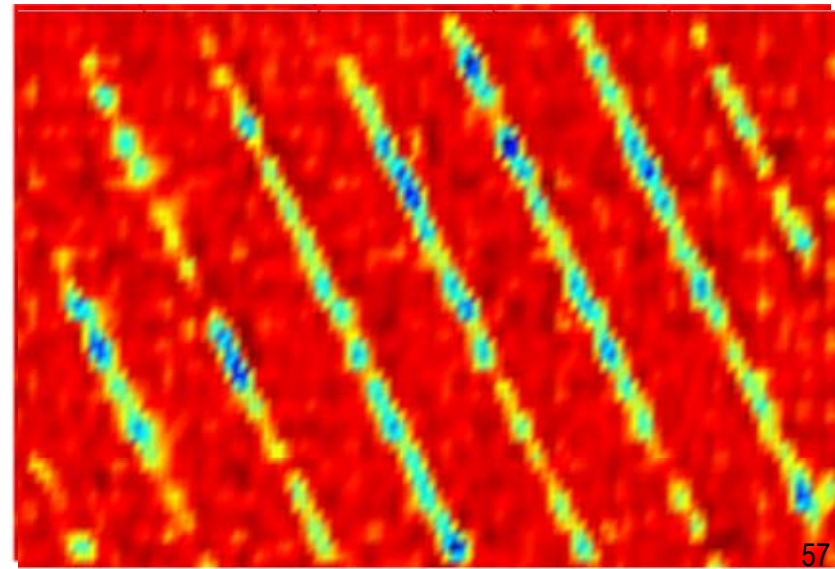


Normal Operation

- ✓ E/ Image: 280 μ J
- ✓ 2.8mW @ 10fps
- ✓ Throughput: 380fps

Wakeup Mode

- ✓ E/ Image: 25 μ J
- ✓ 5 μ W @ 2fps



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Summary & Conclusions

After 30+ years, PMUTs are a disruptive technology for consumer electronics

- PMUTs and other piezo-MEMS are poised for a big impact thanks to maturity of **thin-film piezoelectric materials**.
- **In air:** Tiny 0.5 mm PMUTs have over **1 m range**.
- **In tissue:** pulse-echo fingerprint imaging demonstrated w/ **1.8V supply**.

Acknowledgments



- **Horsley group (BSAC - UC Davis)**
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 - Richard Przybyla, Hao-Yen Tang, Igor Izyumen